Switchable and Tunable Ferroelectric Thin Film Radio Frequency Components

by

Xinen Zhu

A dissertation submitted in partial fulfillment of the requirements for the degree of Doctor of Philosophy (Electrical Engineering) in The University of Michigan 2009

Doctoral Committee: Professor Amir Mortazawi, Chair Professor Xiaoqing Pan Professor Wayne E. Stark Associate Professor Jamie Dean Phillips © Xinen Zhu

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2009

to my wife Fang Ji (Gloria) and my parents

Acknowledgments

I would like to express my deepest gratitude to my advisor, Prof. Amir Mortazawi, for his constant support, guidance and encouragement during my graduate study at the University of Michigan. From him, I learned how to be an independent researcher, as well as a great deal of technical knowledge and skills. I would also like to thank Prof. Xiaoqing Pan, Prof. Wayne E. Stark and Prof. Jamie D. Phillips for their advice and suggestion by being on my dissertation committee.

I would like to especially thank Prof. Jamie D. Phillips to provide the pulsed laser deposition system to this research. Without this system, this work will not even start. I would like to thank Prof. Phillips and former and currents student in his group, including Dr. Ding-Yuan Chen, Willie Bowen, Emine Cagin, Jeff Siddiqui and Weiming Wang, for all the help and discussion on this deposition system.

I would like to thank former and current group members of Prof. Mortazawi, Dr. Ayman Al-Zayed, Dr. Jonghoon Choi, Dr. Xin Jiang, Dr. Lora Schulwitz, Dr. Ali Tombak, Dr. Jin Zhang, Waleed Alomar, Seyit Ahmet Sis, Meng-Hung Chen, Danial Ehyaie, Jia-Shiang (Josh) Fu, Victor Lee, Morteza Nick. Also I would like to thank all the students and staff in the Radiation Lab.

This work will not be possible without the help and support from all the staff in the Lurie Nanofabrication Lab. I would like to express my appreciation to Dr. Dennis Grimard, Gregory Allion, Katharin Beach, Terre Briggs, Timothy Brock, Russ Clifford, Phil Collica, Ning Gulari, Robert Hower, James Kulman, Sandrine Martin, Dennis Schweiger, Edward Tang and Brian VanDerElzen.

I would like to thank all the brothers and sisters at Ann Arbor Chinese Christian Church

and Jiayin Fellowship for their love and support. Especially I would to thank Pastor Teo, Michael Man, Shou-Chin Man, Paul Chao, Alice Chao, Dongxuan Shen, Shiyan Chen for their love, fellowship and spiritual guidance.

Finally I would like to sincerely thank my parents Xuekang Zhu and Peiqi Xu, my wife Fang Ji and my daughter Priscilla Zhu for their constant love and support.

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Chapter 1

INTRODUCTION

Today's wireless communication systems advance steadily with improved system performance, increased functionality, reduced size and cost. For example, mobile phone standards have been evolved from the second generation (2G) with low date rate voice service to the third generation (3G) with higher date rate services such as video calls and wireless broadband data access. As one of the 3G technologies, UMTS ¹ operates in the frequency bands of 850/900/1700/1900/2100 MHz over the globe. For seamless connection to the 3G network, mobile phones are required to operate over all these frequency bands. Other than the cellular service, there are new functional services such as the GPS ² in the 1.5 GHz band, and the Wi-Fi in the 2.4/5.0 GHz bands. Therefore, it is highly desirable for the end users to have a multi-band and multi-mode wireless handheld device. At the same time it is quite a challenge for microwave engineers to have an elegant and cost effective transceiver design for multi-band and multi-mode operations. The conventional approach to design a multi-band multi-mode radio frequency transceiver is to switch among a number of sub-transceivers for each frequency band or mode. This approach is a straightforward implementation, however it results in increased complexity, larger size, and higher cost.

An example using the conventional multi-band transceiver design is the iPhone 3G [3]. It is a tri-band 3G smart phone, and commercially available nowadays. In the transmitter side, it has three TriQuint power amplifier (PA) modules for UMTS 850/1900/2100 MHz bands and a quad-band PA module from Skyworks for the GSM ³ 850/900/1800/1900 MHz

¹Universal Mobile Telecommunications System

²Global Positioning System

³Global Systems for Mobile communications



Figure 1.1 Internal circuit board of an iPhone 3G, taken from www.eetimes.com.

as shown in Figure 1.1 [4]. In order to overcome the shortcomings associated with the current design methodology, electronically tunable circuits have been proposed and investigated for the past few years [5, 6, 7, 8]. Instead of switching among multiple non-tunable transceivers, one single tunable transceiver can be used to dynamically adapt to the active band or mode with the command from the control circuitry, as shown in Figure 1.2. Therefore, transceivers with smaller size, more efficient power usage, and lower cost can be realized for the multi-band and multi-mode wireless handset application.

Another scenario which demands reconfigurable transceivers is the cognitive radio [9, 10]. Today, the majority of the frequency spectrum has already been licensed with the current and next generation services, such as 3G technologies, GPS, Bluetooth, Wi-Fi, ultra-wide band (UWB) and etc. On the other hand, studies have shown that vast portions of the licensed spectra are rarely used. This has initiated the research on the development



Figure 1.2 Tunable front-end block diagram

of cognitive radios, where secondary (i.e., unlicensed) users are allowed to transmit and receive data over portions of spectra when primary (i.e., licensed) users are inactive. In other words, the radio is able to change its transmission or reception parameters such as operation frequency and power level to communicate efficiently avoiding interference with licensed or unlicensed users. This alteration of parameters is based on the active monitoring of several factors in the external and internal radio environment, such as radio frequency spectrum, user behavior and network state. One of key circuits in cognitive radios is a switchable filter bank. It is a band or channel selection system over a wide frequency range through switching among a number of sub-band or channel bandpass filters. In the traditional design of switchable filter banks, there are input and output switches, a number of bandpass filters, and the bias matrix associated with the switches. An example of conventional switchable filter bank [11] is shown in Figure 1.3. Switchable filter banks based on current filter technologies require external switches using solid state or MEMS devices. Incorporating external switches in the path of RF signal results in increased loss, circuit complexity and cost. Instead, intrinscically switchable resonators can be used to design switchable filter banks with less loss, smaller footprint and less cost.



Figure 1.3 A commercial 8-band switchable filter bank from Akon Inc.

The key components for the aforementioned reconfigurable RF and microwave transceivers are reconfigurable devices such as tunable capacitors (varactors) and intrinsically switchable resonators. The change of the capacitance in varactors can be achieved by mechanical tuning [12], magnetical tuning [13] and electronically tuning [14, 15, 16]. Electronically tunable capacitors are preferred due to their small size, light weight and monolithic integration with active devices. Various electronically reconfigurable circuits can be designed, such as tunable antennas (change of the frequency, polarization, radiation pattern, or any combination of them), tunable bandpass filters, adaptive matching networks for PAs, phase shifters, tunable amplifiers, and voltage controlled oscillators. Depending on the functionality of each circuit, the performance gain by using varactors will be improved operation frequency range, efficient power usage, reduced size or less cost. Intrinsically switchable resonators are the resonators that can be turned on and off by the application of the DC bias. The switching process is achieved by the intrinsic property of resonators other than the external switches. For switchable resonators with a miniaturized size and a high Q factor, one can envision to integrate a number of such resonators monolithically for wide-band frequency generation and selection in a compact size with no external switches involved.

Both varactors and switchable resonators can be characterized with the similar performance measures which are summarized below:

- Tunability for varactors (Cmax/Cmin), and frequency tuning for switchable resonators.
- Quality factor.
- Control voltage.
- Power handling capability.
- Linearity.
- Tuning or switching speed.

This work proposes ferroelectric thin films as a viable solution to both high performance RF and microwave varactors and intrinsically switchable resonators. In the next two sections, various varactor and resonator technologies which are currently employed in the wireless communication systems will be discussed to understand their inadequacy for the future challenges and the need of a replacement by the proposed ferroelectric thin films technology.

1.1 An Overview of Varactor Technologies

Microwave varactors are important to the design of tunable microwave circuits. Two varactor technologies are described in this section. They are semiconductor varactor diodes and microelectromechanical system (MEMS) varactors.

1.1.1 Semiconductor Varactor Diodes

A semiconductor varactor diode is a p-n junction diode made of Gallium-Arsenide (GaAs), Silicon (Si) or Silicon-Germanium (SiGe). The depletion area in the p-n junction forms a capacitor, whose capacitance can be varied by changing the reverse bias voltage across the diode. As a mature varactor technology, varactor diodes are commercially available at



Figure 1.4 MEMS varactors

very low cost. The advantages of varactor diodes include large tenability (> 10 : 1), small footprint, fast tuning speed and low control voltage. However, their disadvantage is the poor Q-factor which decreases as the operating frequency increases. Tunable circuits using varactor diodes exhibit considerable amount of loss beyond 5 GHz. Another drawback of semiconductor varactors is their poor power handling capability because the reverse bias requirement doesn't allow for large RF voltage swing across the diode.

1.1.2 MEMS Varactors

Radio frequency (RF) MEMS have been actively researched over the last decade in both industry and academia. They are 3D mechanical structures built on the low cost substrates (alumina, quartz, Si) using mature semiconductor processing and surface micro-machining techniques. Two major RF MEMS devices are switches [17, 18] and varactors [15]. The basic structure consists of two metal traces (signal and ground) separated vertically by an air gap, which forms a parallel-plate capacitor, as shown in Figure 1.4. When a DC bias voltage is applied between the upper bridge and the lower signal trace, the resultant electrostatic force pulls down the thin bridge arm. Therefore the capacitance increases. Further

increase of the DC bias voltage causes collapse of the bridge arm to the signal trace, therefore short circuiting the device. Due to the mechanical rigidness, the change of the bridge gap is limited to one third of its original value. Therefore MEMS varactors suffer from low tunabilities of approximately 1.5:1 with typical tuning voltage requirements in the range of 50-100 V. While MEMS varactors are superior in the Q factor and linearity, they do face practical challenges of reliability and expensive hermetic packaging.

1.2 An Overview of Resonator Technologies

1.2.1 Piezoelectric Materials Based Resonators

Piezoelectricity was first discovered in 1880 by the Curie brothers. The word piezo is derived from Greek piezein, which means to squeeze or stress. As revealed in the name, the piezoelectric effect describes the ability to induce an electrical polarization by the applied mechanical stress in crystals of certain classes. It is also called direct piezoelectric effect. The converse piezoelectric effect is defined as the production of a mechanical stress by the applied electric field. Piezoelectricity is a reversible phenomenon that expresses a linear interaction between mechanical and electrical domains in a single elastic body. This relation is mathematically defined as below.

$$S = s^E T + d^T E \tag{1.1}$$

$$D = dT + \varepsilon^T E \tag{1.2}$$

where S is strain, s is compliance, T is stress, D is electric displacement, d is piezoelectric coefficient, ε is permittivity, E is electric field strength; superscript E indicates a zero or constant electric field, and superscript T a zero or constant stress field.

Crystals can be classified into 32 point groups according to their crystallographic sym-



Piezoelectric Substrate

Figure 1.5 Surface acoustic wave devices

metry: centro-symmetry or non-centro-symmetry. Crystals which belong to the 20 classes of non-centro-symmetry have piezoelectric effect. Common piezoelectric materials include quartz, aluminum nitride (AlN), lead zirconate titanate (PZT).

Depending on the material property and the type of the acoustic wave generated by the piezoelectricity, various acoustic wave resonators can be achieved for different operating frequencies and applications. Two common technologies which are widely used in today's wireless communication systems are surface acoustic wave (SAW) resonators and film bulk acoustic wave resonators (FBAR).

SAW devices rely on the traveling Rayleigh waves along the surface of bulk piezoelectric substrates such as lithium niobate (LiNbO3). As shown in Figure 1.5, SAW filters are simply realized by depositing thin metal electrodes on top of the piezoelectric substrate. The electrodes are in the form of interdigitated transducers (IDT). The input IDT converts the alternating voltage signals into mechanical acoustic waves through the converse piezoelectric effect. The output IDT then converts the delayed acoustic wave back to electrical signals via direct piezoelectric effect. The operating frequency of SAW filters is determined by the periodicity λ of the IDTs (sum of the electrode finger width and spacing) and the acoustic wave velocity u_{ac} of the surface wave as given by (1.3).

$$f_{SAW} = \frac{u_{ac}}{\lambda} \tag{1.3}$$



Figure 1.6 FBAR with (a) air cavity and (b) Bragg reflector

Therefore, the highest achievable operating frequency of SAW filters is limited by the smallest finger width and spacing that can be fabricated by the photolithography process. As the finger width and spacing decrease, the operating frequency increases at the expense of increased ohmic loss and coupling capacitance in the electrodes.

Different from SAW resonators, FBARs rely on the standing bulk acoustic wave across the thickness of the piezoelectric thin film which is sandwiched by two thin metal electrodes. Low cost substrates such as silicon can be used instead of piezoelectric substrates. RF sputtering technique is often used to deposit high quality c-axis oriented piezoelectric thin films such as AlN and zinc oxide (ZnO). In order to minimize the energy loss through the substrate, the resonator needs to be acoustically isolated from the substrate by creating an air cavity under the resonator through silicon micromachining techniques. Another method of isolating the resonator is to use Bragg reflector which is made of multiple pairs of quater-wave high and low acoustic impedance materials, as shown in Figure 1.6. The resonance frequency of FBARs is determined by the total device thickness d and the longitudinal acoustic wave velocity by (1.4).

$$f_{FBAR} = \frac{u_{longitudinal}}{d} \tag{1.4}$$

Compared with SAW filters, FBAR filters demonstrate smaller footprint, lower inser-



Figure 1.7 Contour mode vibrating micromechanical resonator [2]

tion loss, sharper roll-off, higher power handling capability and IC compatibility. FBAR duplexers are commercially available for PCS and WCDMA.

1.2.2 Polysilicon Vibrating Micromechanical Resonators

With the advances in MEMS fabrication technology, 3D objects with a wide variety of geometries can be easily realized in micro scale size. This has helped to accelerate the research in vibrating micromechanical resonators over the past decade. Given the resonator structure and its material properties, the resonance mode shape and its corresponding frequency can be determined. Clamp-clamp beam resonators have been demonstrated at 10 MHz with a Q-factor of 8000 in vacuum [19]. Wine-glass dish resonators can operate at 62 MHz with a Q-factor of 161,000 [20]. Contour mode dish resonators were demonstrated at 1.5 GHz with a Q-factor of 11,555 [2]. The operation of the vibrating micromechanical resonators is based on the mechanical vibration of the resonator body excited by an external force, which is achieved by electrostatic capacitive transduction. A contour mode

dish resonator in the two port configuration is shown in Figure 1.7. The input and output capacitive transducer electrodes are separated from the dish body by a 100 nm air gap. By applying DC bias Vp to the dish and the small signal v_i to the input electrode, the resonator can be excited. The electrostatic force is expressed in (1.5).

$$F_i = \frac{1}{2} \left(\frac{\partial C_1}{\partial r}\right) \left(V_p - v_i\right)^2 = -V_p \left(\frac{\partial C_1}{\partial r}\right) v_i \tag{1.5}$$

As the frequency of v_i matches the natural resonance frequency of the contour mode disk, the disk vibrates in the fashion of radial extraction and contraction around its perimeter by the electrostatic force F_i . Furthemore, the resonator can be turned on or off by the application of the DC bias V_p .

Vibrating micromechanical resonators have many attractive advantages such as, small size, easy integration with silicon IC process, self-switching capability, high Q-factors and single wafer multi-frequency resonators integration. However, these resonators have a very large motional resistance (over tens of k Ω) at the resonance frequency due to the large stiffness of Polysilicon. This creates a significant impedance mismatch to the commonly used 50 Ω system impedance. Filters based on this technology present impractical insertion loss even though the resonator itself is almost lossless [21].

1.3 Ferroelectric Thin Film Technology

Ferroelectric materials are a class of dipolar dielectric materials that exhibit a spontaneous electrical polarization which can be reversed by the application of an external electric field. This unique characteristic has been a very interesting research topic in both fundamental physics as well as in various mechanical, electrical engineering since ferroelectricity was first discovered in 1920.

In normal dielectric materials, the electrical polarization is linearly dependent on the applied electric field, shown in Figure 1.8 (a). Therefore, the resultant permittivity, which



Figure 1.8 Polarization versus electric field for (a) normal dielectrics, (b) ferroelectrics when $T > T_c$ and (c) ferroelectrics with $T < T_c$.



Figure 1.9 (a) The cell structure and (b) the typical CV curve of BST

is equal to the slope of the polarization versus E-field (PE) curve, is a fixed quantity. Ferroelectric materials have a characteristic structural phase transition temperature called the Curie temperature, T_c . Below T_c , ferroelectric materials demonstrate a non-zero spontaneous polarization when no E-field is applied. The spontaneous polarization in ferroelectric materials can be reversed by the application of an external E-field, which results in hysteresis loop, shown in Figure 1.8 (c). Above T_c , the material becomes paraelectric without a spontaneous polarization. At the paraelectric phase, the polarization is a nonlinear function of the applied E-field, as shown in Figure 1.8 (b), resulting in a nonlinear electric field dependent permittivity. This enables one to fabricate electronically tunable capacitors for reconfigurable RF/microwave transceiver application.

Properties	Varactor diode	MEMS varactor	Ferroelectric capacitor
Tunability	high	low	medium
Quality factor	medium	high	medium
Biasing voltage	medium	high	medium
Tuning speed	fast	slow	fast
Power handling	low	medium	high
Linearity	can be improved	high	can be improved [22]

Table 1.1 Comparison of varactor technologies [1]

Barium titanate (BTO), strontium titanate (STO) and barium strontium titanate (BST) are the most popular ferroelectric thin films which are currently studied for tunable RF/microwave circuits. At room temperature, BTO is in the ferroelectric phase with a very high permittivity and tunability. On the other hand, STO, as an incipient ferroelectric with an extrapolated T_c below absolute zero, shows very little tunability at the room temperature. By mixing BTO and STO with certain ratio, BST can be made tunable at room temperature. A typical capacitance versus DC bias voltage curve of BST parallel plate capacitors is shown in Figure 1.9. Advantages of BST thin film based varactors include low dielectric loss for high quality films, high tunability with low tuning voltage for parallel plate capacitors, small footprint due to its high dielectric constant (300 – 500), high power handling capability, and low cost fabrication process. A comparison of BST varactor technologies with the other two aforementioned varactor technologies is shown in Table 1.1.

Ferroelectric materials possess piezoelectric effects due to the spontaneous polarization caused by the non-centrosymmetrical crystal structure. There also exists a quadratic electrostricive effect in ferroelectric thin films. In the paraelectric phase, there's no piezoelectric effect since the crystal structure is centrosymmetrical, therefore the electrostrictive effect dominates. Due to the electrical field dependant polarization, both the piezoelectric and the electrostrictive effects are dependant on the applied electrical field. This unique property can be used to control the mechanical/electrical coupling by the applied DC bias voltage. The converse piezoelectric/electrostrictive effect can be used to generate acoustic waves. For piezoelectric materials, the strength of the acoustic waves can be only changed



Figure 1.10 Switchable ferroelectric FBAR filter bank in reconfigurable front-end transceivers

by the amplitude of the AC electrical signal. In the ferroelectric materials, the generation and strength of the acoustic waves are also dependant on the applied DC electric field. Therefore, novel switchable/tunable acoustic wave resonators with an intrinsic switching property can be designed using ferroelectric materials. Compared with ceramic, SAW and FBAR technologies, switchable filter banks based on ferroelectric thin films based switchable acoustic wave resonators do not require external switches and the associated bias matrix, therefore offer many advantages such as improved performance, lower complexity, smaller footprint and lower cost. A transceiver front-end using switchable ferroelectric FBAR filter bank is shown in Figure 1.10.

1.4 Thesis Overview and Outline

This thesis proposes to use ferroelectric thin films for both low cost high performance varactors and novel switchable acoustic wave resonators at RF and microwave frequencies. This thesis covers a measurement technique for the characterization of ferroelectric thin films at microwave frequencies, a clean room fabrication process and thin film deposition optimization, BST varactors and tunable microwave circuits, novel switchable thickness and lateral mode ferroelectric acoustic wave resonators and filters.

The organization of the thesis is as follows.

Chapter 2 discusses measurement and parameter extraction technique for the characterization of ferroelectric thin films. A two port measurement technique has been proposed in order to determine the loss tangent and permittivity of the BST thin film easily and accurately. Uncertainty studies show that the proposed two port measurement technique is more accurate than the commonly used one port reflection technique by approximately 30%.

Chapter 3 discusses the fabrication process for BST varactors and tunable circuits. BST thin films studied here are deposited by pulsed laser deposition technique. The influence of the deposition conditions on the BST thin film has been studied. By optimizing the substrate temperature, partial oxygen pressure, laser fluence and post process oxygen annealing, BST thin films with a low loss tangent can be achieved. Several fabricated tunable capacitors and circuits are presented.

Chapter 4 presents a tunable microwave filter using BST varactors. Capacitively loaded ring resonators are used since their frequency can be easily tuned and they provide better roll-off. A fully integrated 3 pole filter with a good tunability and moderate insertion loss has been demonstrated.

Chapter 5 discusses the electrostrictive effect in the BST and BTO thin films and its application for novel switchable acoustic wave resonators and filters. Thickness mode resonators are analyzed and simulated. The first working thickness mode BST FBAR with high Q-factors and a comparable electromechanical coupling coefficient to AlN FBARs has been demonstrated. A 1.5 stage ladder type filter using BTO FBARs is designed, fabricated and measured exhibiting a moderate amount of insertion loss. A contour mode acoustic wave resonator using BTO thin films with good Q-factors at the VHF band has been fabricated and measured.

Chapter 6 concludes the thesis and outlines the directions for future work.

Chapter 2

TWO PORT MEASUREMENT TECHNIQUE FOR CHARACTERIZING FERROELECTRIC THIN FILMS

2.1 Introduction

Due to their DC electric field dependent permittivity, ferroelectric thin films have been extensively studied over the past decade for their potential application in tunable RF and microwave components. Ferroelectric thin films also have other advantages such as low loss tangent, high value of dielectric constant, high dielectric breakdown voltage and fast tuning speed. Knowledge of material properties is important for making high performance devices incorporating ferroelectric thin films. For example, thin film's dielectric loss tangent determines the highest possible quality factor (Q-factor) achievable by tunable capacitors. Therefore it is essential to have an accurate measurement method to characterize ferroelectric thin films. Thus, material scientists will be able to tune or optimize the material growth conditions for its improved performance.

Relatively simple measurements using an impedance analyzer can provide reliable results in the low frequency range (up to 100 kHz). However, due to frequency dependence of material properties, low frequency measurement results cannot represent the true material properties at the higher frequency ranges, especially at RF and microwave frequencies. Moreover, parasitics due to the conductors and peripheral circuits become unnegligible at microwave frequencies. Therefore, it is necessary to model the device under the test precisely and de-embed the parasitics completely in order to extract accurately the material properties. Various methods have been proposed in the past to characterize ferroelectric thin films. Each of these techniques has its own advantages and disadvantages. Depending on the type of the device under the test and the frequency range of interest, one method can prevail over others. In this work, a parallel plate capacitor, as a fundamental component, is carefully modeled to characterize the metalic electrodes' parasitic resistance and inductance. A two port measurement technique is proposed to measure and extract the ferroelectric thin film properties up to 10 GHz. Compared with the commonly used one port reflection type measurement technique [23], this new technique provides an easier de-embeding procedure and more reliable results which has been verified through measurement uncertainty analysis.

In section 2.2, several conventional measurement techniques are first reviewed. In section 2.3, modeling of parallel plate capacitors is presented with a distributed circuit analysis. In section 2.4, a two port measurement technique is presented along with the measurement results. In section 2.5, the uncertainty study of both one port and two port measurement techniques is discussed.

2.2 Review of Measurement Techniques for Ferroelectric Thin Films

In order to measure the electrical properties of the dielectric material such as permittivity, loss tangent, leakage current and etc, in the microwave freuqncy regime, it is common to measure the devices which incorporate the dielectric material. For ferroelectric thin films, there are several widely used measurement techniques: coplanar waveguide transmission lines method, planar circuit resonators method and capacitors method. They are reviewed in this section to address their merits and limits.



Figure 2.1 CPW line on ferroelectric thin film

2.2.1 Coplanar Waveguide (CPW) Transmission Lines Method

The coplanar waveguide structure here consists of three layers from bottom to top: the substrate, the ferroelectric thin film and the metal trace, as shown in Figure 2.1. The added ferroelectric thin film increases the effective dielectric constant ε_{eff} , and decreases the characteristic impedance Z_c of the CPW transmission line. Due to the ferroelectric thin film losses, the total loss of the transmission line increases. Thus by measuring the same CPW line with and without the ferroelectric thin film, one is able to extract the material properties of the ferroelectric thin film.

When the transmission line is designed to match the system characteristic impedance [24], the propagation constant can be directly calculated from the transmission coefficient S_{21} by (2.1) and (2.2) [25]

$$\alpha = -\frac{S_{21}}{l} \ (np/m) \tag{2.1}$$

$$\beta = -\frac{\Delta\phi_{S_{21}}}{l} \ (rad/m) \tag{2.2}$$

And the effective dielectric constant ε_{eff} is related to the phase delay of the CPW line

 $\Delta \phi_{S_{21}}$ by (2.3)

$$\Delta\phi_{S_{21}} = -\frac{\sqrt{\varepsilon_{eff}} \cdot f \cdot 2\pi l}{c}$$
(2.3)

By applying the quasi-TEM analysis to this CPW structure, a closed-form expression for ε_{eff} is derived to be (2.4)

$$\varepsilon_{eff} = 1 + q_1(\varepsilon_{r1} - 1) + q_2(\varepsilon_{r2} - \varepsilon_{r1})$$
(2.4)

where

$$k_0 = \frac{S}{S + 2W} \tag{2.5}$$

$$k_1 = \frac{\sinh(\pi S/4h_1)}{\sinh(\pi (S+2W)/4h_1)}$$
(2.6)

$$k_2 = \frac{\sinh(\pi S/4h_2)}{\sinh(\pi (S+2W)/4h_2)}$$
(2.7)

$$q_i = \frac{1}{2} \frac{K(k_i)}{K'(k_i)} \frac{K'(k_0)}{K(k_0)} \quad i = 1, 2$$
(2.8)

and S and W are the gap size and center line width of the CPW line, h_1 is the substrate thickness, h_2 is the ferroelectric thin film thickness, ε_{r1} and ε_{r2} are the dielectric constant of the substrate and the ferroelectric thin film respectively, K(x) is the elliptical integral of the first kind, $K'(x) \equiv K(\sqrt{1-x^2})$, and q_i is the dielectric filling factor.

With the knowledge of the substrate material, the physical dimensions of the CPW line, and the measured phase delay of the CPW line, the dielectric constant of ferroelectric thin film can be determined using (2.3) - (2.8).

The total loss of the CPW structure includes the conductor loss, the ferroelectric thin film loss, the substrate loss and potentially radiation loss. Substrates like sapphire (Al_2O_3) or magnesium oxide (MgO) are very low loss at the microwave frequencies, therefore the substrate loss is negligible. Also radiation loss is negligible because the CPW line width is

much shorter than the operation wavelength. Therefore the total CPW loss is mainly due to the conductor loss and the ferroelectric thin film loss, as given in (2.9).

$$\alpha = \alpha_c + \alpha_{FE} \tag{2.9}$$

where the conductor loss can be calculated by

$$\alpha_c = 8.68 \frac{R_s b^2}{16Z_0 K^2(k)(b^2 - a^2)} (\frac{1}{a} ln(\frac{2a}{\delta} \frac{b - a}{b + a}) + \frac{1}{b} (\frac{2b}{\delta} \frac{b - a}{b + a}))$$
(2.10)

$$a = \frac{S}{2} \tag{2.11}$$

$$b = \frac{S + 2W}{2} \tag{2.12}$$

$$\delta = \frac{t}{4\pi e^{\pi}} \tag{2.13}$$

here R_s is the surface resistance of the metal, Z_0 is the characteristic impedance and t is the conductor thickness.

The ferroelectric loss tangent is related to the dielectric attenuation constant by

$$\alpha_d = 0.91 \sqrt{\varepsilon_{eff}} f(GHz) tan \delta_{\varepsilon_{eff}}$$
(2.14)

$$\alpha_{d} = 0.91 \sqrt{\varepsilon_{eff}} f(GHz) tan \delta_{\varepsilon_{eff}}$$

$$\varepsilon_{eff} tan \delta_{\varepsilon_{eff}} = q_1 \varepsilon_{r1} tan \delta_1 + q_2 \varepsilon_{r2} tan \delta_2$$
(2.14)
(2.15)

From (2.1), the total attenuation constant can be determined. Consequently loss tangent of the ferroelectric thin film can be calculated from (2.9) - (2.15). Applying DC bias voltage between the center line and the ground, the tuning response of dielectric constant and loss tangent can be determined using the aforementioned method.

As a conclusion, this measurement technique provides a straightforward method to extract the permittivity and loss tangent of the ferroelectric thin film over a broad frequency range. However its accuracy is limited due to the approximation of the dielectric filling



Figure 2.2 CPW resonator on ferroelectric thin film

factor which describes how the electric and magnetic fields are distributed in the ferroelectric thin film and substrate. Furthermore, this technique applies only for the case when the ferroelectric thin film is deposited on the dielectric substrate. The extracted material properties cannot accurately represent the thin film which is deposited on a conductor, for example in case of parallel plate capacitors. Because the way how the FE thin film grows strongly depends on the underlying layer's properties, such as chemical composition, thermal expansion coefficient, surface roughness and etc.

2.2.2 Planar Printed Circuit Resonators Method

Microwave resonators are often used to facilitate the evaluation of the material properties. Within this category, there are various kinds of resonators for different applications, such as cavity resonators, microstrip ring resonators, CPW half wavelength resonators and capacitively loaded resonators. Among them, planar circuit resonators are more attractive due to their ease of implementation, compact size and versatile design, as compared with the cavity resonators. For ferroelectric thin films, planar printed circuit resonators are preferred due to the easiness to incorporate thin films. One example using a CPW line resonator is shown in Figure 2.2 [25]. The ferroelectric thin film is deposited on a substrate, then the metal trace is put on top of the ferroelectric thin film. The total effective dielectric constant

of the CPW resonator is determined by (2.16)

$$\varepsilon_{eff} = \left(\frac{c}{2f_0 l}\right)^2 \tag{2.16}$$

where c is the speed of light in vacuum, f_0 is the resonance frequency of the CPW resonator, l is the length of the resonator. By applying a similar analysis using conformal mapping as described in previous section, the permittivity of the ferroelectric thin film can be calculated by (2.4).

From the resonant frequency f_0 and the 3 dB bandwidth Δf , the effective dielectric loss tangent is obtained by (2.17)

$$tan\delta = \frac{2\Delta f}{f_0} \tag{2.17}$$

As before substrate and radiation loss are negligible here. Therefore the effective loss tangent is due to the ferroelectric thin film dielectric loss and the conductor loss. Same analysis as in the previous case can be used to extract the true dielectric loss tangent of thin film ferroelectrics. An alternative way is to use superconductor, such as YBCO. In this case the conductor loss can be assumed to be zero.

In conclusoin the measurement technique based on planar circuit resonators is very simple in the implementation and post-measurement data process, and it is accurate. However a main drawback is that this technique applies only to a single frequency. It's impossible to characterize the material in a broad frequency range using this characterization method.

2.2.3 Capacitors Method

Ferroelectric thin films have been under active research for decades for the applications from high density DRAM, non-volatile computer memory (FeRAM), high-K gate transistors and tunable microwave circuits. In all these applications, the fundamental component is a capacitor in forms of either parallel plate or interdigital. Therefore, capacitors are a



Figure 2.3 Conventional capacitors and the model

straightforward media to characterize the ferroelectric thin films.

A capacitor can be modeled with the lumped circuit elements shown in Figure 2.3. This lumped circuit model includes a core capacitor C, a series resistor R_s which represents the parasitic conductor and contact resistance, an series inductor L_s which represents the parasitic conductor inductance, and a shunt resistor R_p which represents the dielectric loss. The total impedance is given by

$$Z_{tot} = R_s + j\omega L_s + \frac{1}{\frac{1}{R_p} + j\omega C}$$
(2.18)

The capacitance can be determined by

$$\omega C = imag(\frac{1}{Z_{tot} - R_s - j\omega L_s})$$
(2.19)

For parallel plate capacitors, the capacitance is related to the relative dielectric permit-
tivity (ε_r), electrode area (A) and dielectric thickness (d) by

$$C = \frac{\varepsilon_0 \varepsilon_r A}{d} \tag{2.20}$$

The total quality factor (Q factor) can be directly calculated by

$$Q_{tot} = \frac{imag(Z_{tot})}{real(Z_{tot})}$$
(2.21)

and the loss tangent is determined by (2.22) assuming that the parasitics R_s and L_s are known.

$$tan\delta = -\frac{real(Z_{tot} - R_s - j\omega L_s)}{imag(Z_{tot} - R_s - j\omega L_s)}$$
(2.22)

2.3 Modeling of Parallel Plate Capacitors

A simple structure for a parallel plate capacitor consists of three layers: a bottom metal electrode, a ferroelectric thin film and a top metal electrode. The two metal electrodes exhibit the parasitic resistance and inductance which lower the total Q-factor and self resonance frequency. The parasitic resistance increases as the operation frequency increases due to the skin depth effect. Therefore in order to extract the material loss tangent accurately, the effect of the electrodes must be studied and modeled carefully.

A first-thought estimation of the electrodes resistance is equal to the RF resistance of the electrodes by

$$R_s = \frac{L}{\sigma W t} \tag{2.23}$$

where σ is the metal conductivity, and L, W and t are the length, width and thickness of the electrode. However this is wrong! This calculation is valid under the condition that the current density on the electrode is uniform. In parallel plate capacitors, it is interestingly



Figure 2.4 RF current density on a) the parallel plate capacitor and b) the electrode only

not the case.

There exist two kinds of RF current in parallel plate capacitors: the conduction current flowing horizontally along the electrodes, and the displacement current flowing vertically in the dielectrics. As passing along the top electrode, the conduction current converts to the displacement current gradually. Therefore, on the top electrode the RF current density changes from its maximum to minimum or zero from one end of the electrode to the other end. While on the bottom electrode, the conduction current builds up gradually because the displacement current is converted back to the conduction current. This process is illustrated in Figure 2.4.

In order to find out the equivalent resistance by the electrodes qualitatively, a distributed circuit model of the capacitor is studied here. The distributed circuit for capacitor is equally divided into n small cells along the electrode. The equivalent circuit of each cell consists of a small resistance (ΔR) and an inductance (ΔL) in series for the top and bottom electrode, and a shunt small capacitance (ΔC), which are given by



n cells

Figure 2.5 Circuit model of parallel plate capacitors



Figure 2.6 Simplified circuit model of parallel plate capacitors

$$\Delta R = \frac{R'}{n} \tag{2.24}$$

$$\Delta L = \frac{L}{n} \tag{2.25}$$

$$\Delta C = \frac{C_{tot}}{n+1} \tag{2.26}$$

where R' and L' are the resistance and inductance of the electrode with uniform current density, and C_{tot} is the total capacitance given by (2.20). The distributed circuit model is shown in Figure 2.5. Since top and bottom electrodes present equal parasitics, a simplified distributed circuit model with the bottom electrode only is shown in Figure 2.6.

This circuit is indeed a transmission line loaded with an open circuit at one end. Using

the tranditional transmission line theory, the propagation constant and the characteristic impedance are given by

$$\gamma = \sqrt{zy} = \sqrt{(\Delta R + j\omega\Delta L)j\omega\Delta C}$$
(2.27)

$$Z_0 = \sqrt{\frac{z}{y}} = \sqrt{\frac{\Delta R + j\omega\Delta L}{j\omega\Delta C}}$$
(2.28)

where z is the series impedance and y is the shunt admittance per unit length. The input impedance of an open circuited transmission line with length L is given by

$$Z_{in} = Z_0 coth(\gamma L) \tag{2.29}$$

Using the Laurent series expansion, (2.29) can be approximated to

$$Z_{in} \approx Z_0 \left(\frac{1}{\gamma L} + \frac{\gamma L}{3}\right) \tag{2.30}$$

With (2.25) and (2.26), the input impedance of the capacitor is derived as (2.31)

$$Z_{in} \approx \frac{R' + j\omega L'}{3} + \frac{1}{j\omega C_{tot}}$$
(2.31)

From (2.31), the contribution due to the top electrode is only 1/3 of the impedance of a same size metal piece. The bottom electrode will have the same impedance as the top electrode. Therefore the total parasitic impedance of the electrodes in parallel plate capacitors has a scaling factor of 2/3, which is the same as reported in [26].

2.4 De-embedding Techniques of Parallel Plate Capacitors

In the on wafer microwave characterization, modeling and de-embedding of the parasitics are an important and difficult task in order to retrieve the real performance of the device under test (DUT) which has to be embedded in a 'probe friendly' structure. For the parallel plate capacitors using ferroelectric thin films, these parasitics are originated from:

- Probe contact pads
- Interconnecting circuitries from probe contact pads to the capacitors
- Any discontinuity
- Top and bottome electrodes
- Probe contact resistance

The standard calibration methods like short-open-load-through (SOLT) and throughreflection-line (TRL) calibrate the reference plane up to the probe tips, removing all the effects from equipments and cables. However they are insufficient to de-embed the above parasitics. With the introduction of some additional on-wafer structures, the real material properties of ferroelectric thin films can be extracted.

2.4.1 One Port Measurement Technique Using Signal-Ground (SG) Probes

There are a total of three kinds of structure fabricated on the same wafer: the parallel plate capacitors, and two short standards with different lengths [23]. Their physical layouts and the lumped circuit models are shown in Figure 2.7. They can be modeled as a series impedance individually, Z_{s1} for short standard 1, Z_{s2} for short standard 2 and Z_{mc} for the unde-embedded capacitor. The input impedance of these three structures can be obtained



Figure 2.7 Physical layouts and circuit models for one port measurement using SG probe

from one port reflection coefficient S_{11} by

$$Z_{in} = Z_0 \frac{1 + S_{11}}{1 - S_{11}} \tag{2.32}$$

and

$$Z_{s1} = R_1 + j\omega L_1 \tag{2.33}$$

$$Z_{s2} = R_2 + j\omega L_2 \tag{2.34}$$

$$Z_{mc} = R_1 + j\omega L_1 + R_e + j\omega L_e + \frac{1}{G_d + j\omega C}$$

$$(2.35)$$

 Z_{s1} represents the parasitics due to the probe pads, interconnection lines and the discontinuity between them. By subtracting Z_{s1} from Z_{s2} , the impedance of line having the same length and width as the capacitor electrodes can be obtained. The parasitic impedance due to the electrodes ($R_e + j\omega L_e$) is equal to $\frac{2}{3}$ of the difference between Z_{s1} and Z_{s2} , as shown in the previous section. With the knowledge of all these parastics, the capacitor impedance can be calculated by

$$Z_c = Z_{mc} - Z_{s1} - \frac{2}{3}(Z_{s2} - Z_{s1})$$
(2.36)

Consequently the loss tangent and capacitance are given by

$$tan\delta = \frac{1}{G_d j\omega C} = -\frac{real(Z_c)}{imag(Z_c)}$$
(2.37)

$$C = -\frac{1}{imag(Z_c)\omega}$$
(2.38)

However the accuracy of the SG probe diminishes at high microwave frequencies due to unbalanced field termination at the probe tip. Instead, ground-signal-ground (GSG) probes are more accurate for high frequency on wafer measurements.

2.4.2 One Port Measurement Technique Using GSG Probes

Coplanar waveguide (CPW) probe structure is used to embed the DUT when the GSG probe is used for measurement. In addition to the series parasitic impedance, there is a shunt parastic admittance between the signal line and the two ground pads, as shown in Figure 2.8. To de-embed them, two additional standards are needed in which the DUT is replaced by an open or a short circuit [27]. The de-embed procedures are summerized below.

1. Measure the DUT, the short and open standards using GSG probe with the network analyzer. Using (2.32), convert the measured one port reflection coefficients to the respective input impedances Z_{meas} , Z_{short} and Z_{open} .

2. The series parasitic impedance Z_s is equal to Z_{short} .



Figure 2.8 Physical layout and circuit model for one port measurement using GSG probes

3. Subtract Z_{open} from Z_{short} , the shunt parasitic admittance Y_p is obtained by

$$Y_p = \frac{1}{Z_{open} - Z_{short}} \tag{2.39}$$

4. Finally the DUT impedance Z_{DUT} is calculated by

$$Z_{DUT} = \frac{1}{\frac{1}{Z_{meas} - Z_s} - Y_p}$$
(2.40)

By applying this de-embed procedure to capacitors, short standard 1 and 2, then using (2.33) - (2.38), one can extract loss tangent and capacitance for capacitors.

2.4.3 Two Port Measurement Technique Using GSG Probes

The impedance of high Q-factor capacitors is approximately equal to $R_s + j\omega C$. When the parasitic resistance is much smaller than the reactance, the magnitude of the reflection coefficient is close to 1. The network analyzer has a larger uncertainty in the measured reflection coefficient for unmatched loads ($|S_{11}| = 1$) than matched loads ($|S_{11}| = 0$). Furthermore,



Figure 2.9 Physical layout and circuit model for two port measurement using GSG probes

the conversion for S_{11} to input impedance Z_{in} using (2.32) in the one port measurement technique is sensitive to the measurement error in S_{11} because the denominator is close to zero when $|S_{11}| = 1$. Therefore, a two port measurement technique is presented in order to improve the measurement accuracy [28].

In a two port measurement setup, two GSG probes are used to measure the capacitors, standard 1 and 2 in CPW structures, as shown in Figure 2.9. Similar to the one port configuration using GSG probes, there are both series and shunt parasitics in the two port structures. Instead of using additional short and open circuit standards to de-embed these parasitics as is done in the one port technqiue using GSG probes, the impedance of the DUT can be extracted by converting the two port S-parameters to ABCD parameters. For the two port configuration, the corresponding ABCD matrix is given by

$$\begin{vmatrix} A & B \\ C & D \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ Y_p & 1 \end{vmatrix} \begin{vmatrix} 1 & Z_{DUT} \\ 0 & 1 \end{vmatrix} \begin{vmatrix} 1 & 0 \\ Y_p & 1 \end{vmatrix} = \begin{vmatrix} 1 + Y_p Z_{DUT} & Z_{DUT} \\ 2Y_p + Y_p^2 Z_{DUT} & 1 + Y_p Z_{DUT} \end{vmatrix}$$

The B parameter is equal to the impedance of the DUT which includes the series parasitics such as, probe pads and interconnects. After calculating the B parameters for the capacitor, line standard 1 and 2 by using (2.41)

$$Z_{DUT} = B = Z_0 \frac{(1+S_{11})(1+S_{22}) - S_{12}S_{21}}{2S_{21}}$$
(2.41)

The loss tangent and the capacitance of the ferroelectric thin film capacitors can be determined by using (2.33) - (2.38).

In two port S-parameter measurement, the reflection coefficient at both ports are measured with the other port terminated with the system characteristic impedance Z_0 of the network analyzer, which is normally equal to 50 Ω . Therefore, for high Q-factor capacitors, both S_{11} and S_{22} are close to zero instead of 1 in the one port measurement technique. With S_{21} and S_{12} are close to 1, (2.41) is not sensitive to the measured s-parameters' errors. As a result, the two port measurement technique is more accurate than the one port reflection technique. A detailed uncertainty analysis of both techniques will be presented to verify this in the next section.

2.5 Uncertainty Study

For a function *y* dependent on a number of measured quantities x_i , the uncertainty is calculated by (2.42)[29] under the assumption that x_i are uncorrelated.

$$\frac{\delta y}{y} = \left(\sum_{i} \left(\frac{\delta x_i}{x_i}\right)^2 \left(S_{x_i}^y\right)^2\right)^{0.5}$$
(2.42)

where

$$S_{x_i}^y = \frac{x_i}{y} \frac{\partial y}{\partial x_i}$$
(2.43)

In characterizing BST thin films, the final extracted quantities such as loss tangent and the capacitance or dielectric constant, are obtained from the measured one port or two port S-paramters. Therefore, the uncertainty of the loss tangent and the capacitance is related to the uncertainty of the measured S-paramters through (2.42-2.43). The uncertainty of the S-paramters measured by the network analyzer are provided by the manufacturer [30]. By lowering the IF bandwidth and increasing the average factor, the uncertainty of the S-parameters can be minimized, as shown in Figure 2.10 and 2.11.

In one port measurement technique, the loss tangent and the capacitance are determined by (2.32-2.38). Then by applying (2.42, 2.43) to (2.37, 2.38), the uncertainty of the loss tangent and the capacitance are derived to be:

$$\frac{\Delta tan\delta}{tan\delta} = \frac{1}{tan\delta} \left[\Delta |S_{11}|^2 \left(\frac{|S_{11}|^2 + 1}{2|S_{11}|^2 sin\phi_{11}} \right)^2 + (\Delta\phi_{11})^2 \left(\frac{1 - |S_{11}|^2}{2|S_{11}|sin^2\phi_{11}} cos\phi_{11} \right)^2 \right]^{1/2}$$
(2.44)

$$\frac{\Delta C}{C} = \frac{Y_0}{\omega C} \left\{ A + B \right\}^2 \tag{2.45}$$

where

$$A = (\Delta |S_{11}|)^2 \left[\frac{2sin\phi_{11} - 2|S_{11}|^2 cos\phi_{11}}{(1 + 2|S_{11}| cos\phi_{11} + |S_{11}|^2)^2} \right]^2$$
(2.46)

$$B = (\Delta\phi_{11})^2 \left[\frac{2|S_{11}|\cos\phi_{11} + 4|S_{11}|^2 + 2|S_{11}|^3\cos\phi_{11}}{(1+2|S_{11}|\cos\phi_{11} + |S_{11}|^2)^2} \right]^2$$
(2.47)

where $|S_{11}|$ and $\Delta \phi_{11}$ are the measured S_{11} magnitude and phase, $\Delta |S_{11}|$ and $\Delta \phi_{11}$ are the error of the magnitude and phase of the reflection coefficient, Y_0 is characteristic admittance, and ω is the angular frequency.

From (2.44), it is clear that the uncertainty of the extracted loss tangent comes from two parts: error in the magnitude and phase of S_{11} . Since the error from the phase is negligible



Figure 2.10 Comparison of the uncertainty of S_{11} magnitude and phase under different IF BW and average factors



Figure 2.11 Comparison of the uncertainty of S_{21} magnitude and phase under different IF BW and average factors

compared with that from the magnitude, (2.44) can be rewrited as

$$\frac{\Delta tan\delta}{tan\delta} \cong \frac{1}{tan\delta} \left(\Delta |S_{11}| \left(\frac{|S_{11}|^2 + 1}{2|S_{11}|^2 sin\phi_{11}} \right) \right)$$
(2.48)

Since S_{11} is close to 1 for BST varactors measured by one port measurement technique, the minimum value of the term in parentheses is equal to 1, as given in (2.49).

$$min\left(\frac{|S_{11}|^2 + 1}{2|S_{11}|^2 sin\phi_{11}}\right) = 1$$
(2.49)

Thus the minimum uncertainty of the loss tangent is determined solely by the actual dielectric loss tangent and the error of the magnitude of the reflection coefficient which is set by the network analyzer in the setup, by

$$\frac{\Delta tan\delta}{tan\delta} \cong \frac{1}{tan\delta} \Delta |S_{11}| \tag{2.50}$$

It is shown in Figure 2.10, the minimum error of the reflection coefficient magnitude is about 0.008 at the lowest frequency. Therefore, the uncertainty of the loss tangent will be very big for low loss material, and smaller for lossy ones. The uncertainty in the loss tangent for BST thin films with different loss tangent values are calcualted and plotted in Figure 2.12. For example, with loss tangent of 0.01, the uncertainty is larger than 250%, while for loss tangent of 0.1, the uncertainty can be as low as 50%. The discontinuity in Figure 2.12 is due to the band change in the network analyzer, resulting different errors for the reflection coefficient.

In two port measurement technique, the loss tangent and the capacitance are the function of 4 S-paramters: S_{11} , S_{22} , S_{12} and S_{21} . Because the varactors are passive components, and the varactor layout is symmetric, it can be assumed that $S_{11} = S_{22}$ and $S_{12} = S_{21}$. Applying (2.42, 2.43) to the two port measurement technique, the uncertainty of the loss tangent and capacitance can be determined. The explicit expressions are too complex to obtain. Instead, numerical programs are used to plot the uncertainty of the loss tangent and



Figure 2.12 Comparison of the uncertainty in the loss tangent for BST thin films with different loss tangent values using one port measurement technique.



Figure 2.13 Comparison of uncertainty of loss tangent using one port and two port measurement techniques

the capacitance determined by two port measurement technique.

It is shown in Figure 2.13 and 2.14 that the two port measurement technique is more accurate than the one port measurement technique, with 30% improvement of uncertainty



Figure 2.14 Comparison of uncertainty of capacitance using one port and two port measurement techniques

in both loss tangent and capacitance. Therefore, for characterization of ferroelectric thin films and varactors at the microwave frequency, the two port measruement technique is recommended because it is not only simpler to implement but also more accurate than conventional one port reflection type measurement technique.

2.6 Measurement Results

The two port measurement technique has been applied to the BST tunable capacitors. It is shown in Figure 2.15 that without the proper de-embed technique, the extracted loss tangent of BST thin films is erroneously larger than its real value. The extracted loss tangent, permittivity of BST thin films are shown in Figure 2.16 and 2.17.



Figure 2.15 Comparison of loss tangent with/without de-embeding using two port measurement technique

2.7 Conclusion

Commonly used measurement and deembedding techniques to characterize ferroelectric thin films and varactors are discussed in this chapter. CPW structures are not suitable for characterization of parallel plate capacitors because the deposited ferroelectric thin film exhibits different material and electrical properties with or without metal bottom electrode. Instead, measurements of capacitors are a straightforward way. The conventional one port reflection type measurement technique is not accurate because the S_{11} of low loss capacitors measured from the network analyzer is very sensitive to the errors. A two port measurement technique is proposed to provide not only an easier deembedding process but also better acuracy. The uncertainty study of both techniques shows that two port measurement technique improves the uncertainty of the extracted loss tangent and capacitance by 30%.



Figure 2.16 Extracted loss tangent of the BST thin film



Figure 2.17 Extracted relative permittivity of the BST thin film

Chapter 3

FABRICATION OF FERROELECTRIC THIN FILM VARACTORS AND THEIR APPLICATION IN MICROWAVE TUNABLE CIRCUITS

In this chapter, fabrication of ferroelectric thin film varactors and their application in microwave tunable circuits are discussed in details. The fabrication process includes the thin film deposition optimization and the clean room fabrication process. Pulsed laser deposition technique (PLD) is used to deposit ferroelectric thin films. Thin film deposition parameters are studied and optimized in order to achieve good quality BST thin films for the design of microwave varactors. The goal is to fabricate BST thin films with a low loss tangent and a high permittivity tunability. A full clean room fabrication process is developed. Various microwave tunable circuits are demonstrated using this fabrication process.

3.1 Optimization of Ferroelectric Thin Films Deposited by Pulsed Laser Deposition

As the semiconductor industry advances, thin film deposition techniques become more and more mature. Ferroelectric thin films have been successfully deposited by various deposition methods: molecular beam epitaxy (MBE) [31], metal-organic chemical vapor deposition (MOCVD) [23, 32], sol-gel [33], RF sputtering [16] and pulsed laser deposition (PLD) [34]. It is difficult to choose one as the best technique because each has its own merits and limits depending on the application in mind and the available budget. In this work PLD process is used because of its advantages such as:

• Maintaining stoichiometry of deposited thin films as the target material

- High deposition rate (about 10 nm/min)
- Low process temperature (about 600 °C)
- Multi-material deposition without breaking the chamber vacuum
- · Low cost multi-chamber deposition using one laser source

On the other hand, PLD process suffers from shortcomings such as:

- Nonuniform thin films
- Small useful deposition areas (1cm by 1cm)
- Particulate and defects
- Target surface modification due to the laser ablation

Techniques like mechanical particle filter and substrate rotation can be used to decrease the number of small particulate and to improve the film uniformity at the expense of the deposition rate. In general, PLD is more favorable for academic and laboratory research as opposed to industry manufacturing.

3.1.1 Pulsed Laser Deposition Process

Pulsed laser deposition, as implied by its name, utilizes a laser to deposit thin films. The setup of PLD is quite simple, as shown in Figure 3.1. It consists of a laser source, a vacuum chamber and a gas pressure and substrate temperature control system. Inside the vacuum chamber, there exist a target mount and a temperature controlled substrate. Though the physical process and mechanics of PLD process are very complicated and are subject of on-going research, they can be briefly described as:

- A focused high energy density laser $(1 2J/cm^2)$ hits the rotating target material
- The laser energy causes the ablation and evaporation process on the target surface
- The ablated target materials in the forms of electrons, ions, neutrals and ionized species form an ionized plasma plume
- The plume interacts with the ambient reactive gas.
- The plume reaches the heated substrate and deposits the target material on it.



Figure 3.1 Illustration of a typical PLD setup.

3.1.2 Deposition Parameter Optimization

In PLD process, the deposited thin film quality is strongly dependent on the deposition parameters such as substrate temperature, reactive gas pressure, laser fluence and post process annealing. By varying each parameter, BST thin films are deposited and studied. Parallel plate capacitors are then fabricated and measured using two port measurement technique described in chapter 2 to extract the BST loss tangent, permittivity under different DC bias voltage. Sapphire is used as the substrate because it presents a very low loss at microwave frequencies and its thermal expansion coefficient (CTE) is close that of BST thin films. Both the bottom and top electrode are made of platinum because platinum has a similar CTE to BST thin films and it has high conductivity. The BST target is a 2 inch high purity $Ba_{0.5}Sr_{0.5}TiO_3$ ceramic disk.

The effect of substrate temperature on the performance of BST thin films

The substrate temperature plays an important role in determining the crystalline quality of the BST thin film by affecting the adatom's mobility. From low temperature to high temperature, the crystalline phase usually varies from amorphous, to polycrystalline and to highly



Figure 3.2 C-V tuning curves for BST thin films deposited at 500, 600 and 700 degrees

oriented thin films. Usually BST thin films with a better crystalline quality can achieve a better tunability. Therefore high substrate temperature is desired for highly tunable BST thin films. On the other hand, it is reported that higher loss is unfortunately associated with the higher tunability in BST thin films, thus degrading the device Q-factor [35]. This may be due to the strain caused by the thermal mismatch between the BST thin film and the underneath electrode and substrate. In some cases, the large thermal mismatch due to the high substrate temperature causes cracks/peelings in the deposited thin films during the cooling phase.

BST thin films are deposited at three different substrate temperatures: 500 °C, 600 °C and 700 °C with all the other deposition parameters kept the same. It's found that 500 °C BST thin films can be barely tuned. As the temperature increased to 600 °C and 700 °C, the tunability is increased to 2:1 and 3:1 respectively, as shown in Figure 3.2.



Figure 3.3 Illustration of the oxygen vacancies in the BST thin films

The effect of partial oxygen pressure on the performance of BST thin films

Since BST is an oxide, oxygen is introduced during the deposition in the PLD system. The oxygen flow rate and pressure are controlled and monitored during the process. Studies show that high dielectric loss is partly attributed to the oxygen vacancies in the BST thin films which act like charged defects [36]. The defects are distributed unevenly in the deposited thin film body, as well as at the interface between the thin film and the electrode, as illustrated in Figure 3.3. In order to reduce the oxygen vacancies, two approaches are taken in this study

- 1. To increase the partial oxygen pressure
- 2. Post process annealing in the oxygen environment [37]

Three samples are prepared with different partial oxygen pressures and annealing condition: 120 milli-Torr (mTorr) oxygen without annealing, 300 mTorr oxygen without annealing and 300 mToor oxygen with annealing. The substrate temperature is kept at 650 °C, and the laser fluence of $1 J/cm^2$ is used. The measured loss tangents of the BST thin films are shown in Figure 3.4.

As the partial oxygen pressure increased from 120 mTorr to 300 mTorr, the measured loss tangent of BST thin films is decreased by 50%. After the post annealing in flowing oxygen environment at 500 °C for 30 minutes, the measured loss tangent of BST thin films is further decreased by another 100%. Therefore the increase of partial oxygen pressure



Figure 3.4 Loss tangent of the BST thin films under different partial oxygen pressure and annealing conditions

and post process oxygen annealing are very effective to reduce the dielectric loss at the microwave frequencies.

The effect of laser fluence on the performance of BST thin films

The laser fluence, or the laser power density, is another important parameter in PLD process. It is defined as the laser power on the material target surface per unit area, given by (3.1)

$$laser fluence = \frac{Output \ laser \ power}{laser \ spot \ area \ on \ target} (J/cm^2)$$
(3.1)

Sufficient laser fluence is needed to ablate the target materials while keeping the material's stoichiometry. The laser fluence can be adjusted by either varying the output laser power or the laser spot area on the target through an external optics system. A smaller spot size of the focused laser beam is preferred because the required output laser power is smaller, thus laser lifetime can be increased.



Figure 3.5 Loss tangent of the BST thin films under two different laser fluence

BST thin films are deposited with two different laser fluence levels. The laser spot size is kept as 0.08 cm^2 . The substrate temperature is kept at 650 °C, and the partial oxygen pressure is 300 mTorr. A post process annealing process is applied to BST thin films. The measured loss tangents of BST thin films are extracted and shown in Figure 3.5. When the laser fluence is increased from 0.44 to $1 J/cm^2$, the loss tangent is reduced by half.

The effect of post process oxygen annealing on the performance of BST thin films

It has been shown that the post process oxygen annealing not only can improve the dielectric Q factor but also the tunability of BST thin films [38]. The oxygen vacancies at the electrode/thin film interface may form a positively or negatively charged trapped-oxygen site. This can cause local polarizations, resulting in hysteresis in tuning response. The post process oxygen annealing can be used to reduce oxygen vacancies, thus recover the paraelectric tuning response of BST thin films [39].

Post process oxygen annealing is performed in a tube furnace at 500 °C with flowing



Figure 3.6 C-V tuning curves of the BST thin film (a) without and (b) with the post process oxygen annealing

oxygen for 30 minutes. The BST thin film is deposited at 650 °C, 300 mTorr partial oxygen pressure, and the laser fluence of $1 J/cm^2$. In the tunability measurement, the DC bias voltage is swept from -10 V to 10 V, then back to -10 V. This DC bias sweep scheme is repeated for several times. Without the post process oxygen annealing, the measured C-V response is asymmetric about 0V as shown in Figure 3.6 (a). The capacitances for forward (-10 V to 10 V) bias are different than the capacitances for backward (10 V to -10 V) bias. This can be attributed to a built-in voltage potential existed at the electrode-thin film interface. After the post process oxygen annealing, the normal paraelectric response of the $Ba_{0.5}Sr_{0.5}TiO_3$ thin film is recovered as shown in Figure 3.6 (b).

After the deposition conditions are studied and optimized, a PLD process to achieve high Q-factor microwave varactor using BST thin films is summarized below:

- Substrate temperature of 650 °C.
- Partial oxygen pressure of 300 mTorr.
- Laser fluence of $1 J/cm^2$
- Post process oxygen annealing at 500 °C, flowing oxygen environment for 30 minutes.

BST varactors are measured to achieve Q-factors above 100 in the lower GHz range with this PLD process as shown in Figure 3.7. The deposited BST thin films are polycystalline thin films with a < 111 > preferred orientation. The measured X-ray diffraction (XRD) is shown in Figure 3.8.

3.2 Clean Room Fabrication Process

All the fabrication is carried out in the Michigan Lurie Nanofabrication Facility under class 1000/100 clean room environment. There are more than 10 steps for the fabrication of ferroelectric thin film based tunable capacitors and circuits. The graphic illustration of the fabrication flow is shown in Figure 3.9. The substrate used is a single side polished 430



Figure 3.7 Device Q factor of the BST varactor with optimized PLD deposition conditions



Figure 3.8 XRD measurement of BST thin films with optimized PLD deposition conditions

 μm c-plane sapphire substrate. Each step is listed below and the detailed recipes for each step are listed in the Appendix A.

- 1. Cleave, and clean sapphire substrate with Acetone and IPA.
- 2. E-beam evaporation and liftoff bottom electrode (Ti/Pt 30/1000 Å).
- 3. BST deposition using PLD.





- 4. Etching silver paint by the gold etchant.
- 5. E-beam evaporation and liftoff top electrode (Pt 1000 Å).
- 6. Post process annealing.
- 7. Patterning BST thin film using diluted HF solution (HF:DI water 1:10).
- 8. DC sputter and liftoff high resistivity SiCr thin film (700 Å).
- 9. E-beam evaporation and liftoff contacts (Ti/Au 50/3000 Å).
- 10. SiO₂ passivation using PECVD and wet etching in BHF (5000 Å).
- 11. E-beam evaporation and liftoff circuitry seed layer (Ti/Au 50/5000 Å).
- 12. Gold plating to $10 \ \mu m$.
- 13. Seed layer etch back.
- 14. Dice off devices (option).



Figure 3.10 Single and 5x5 stacked BST varactor

3.3 Microwave Tunable Circuit Applications

Based on this fabrication process, both BST varactors and tunable microwave circuits using BST varactors are fabricated. Figure 3.10 shows a single BST varactor and a 5x5 stacked BST varactor. By stacking several BST varactors in series with a proper biasing network, the device linearity can be improved greatly while the total device quality factor and tunability are maintained [22, 40].

A phase shifter and an impedance tuner are demonstrated using BST varactors, as shown in Figure 3.11 and 3.12. They are designed by another colleague Josh Fu in our group. Details of theory and design are described in his PhD dissertation. The phase shifter has an insertion loss less than 2 dB at 2.4 GHz, and a 90 degree phase change with 25 V bias. Using stacked BST varactors, the intermodulation distortion is improved, with IIP3 measured to be larger than 40 dBm [40]. The impedance tuner, composed of a phase shifter and a variable transformer, is designed based on all-pass networks [41]. On-wafer measurement results show that, at 1.8 GHz, impedance transformation ratio of 4 can be achieved and the dissipation loss for all biasing voltages (0 to 18 V) is less than 5.5 dB.







Figure 3.12 BST varactor based impedance tuner

3.4 Conclusion

Deposition of BST thin films using PLD system has been studied. The deposition conditions are optimized in order to achieve microwave varactors with high Q-factor and moderate tunability. The substrate temperature, partial oxygen pressure, laser fluence and post process oxygen annealing are found to have major impacts on the deposited BST thin films electrical properties such as loss tangent, relative permittivity and tunability. High Q-factor microwave varactors have been fabricated with the optimized PLD conditions. A clean room fabrication process is developed. BST varactors and tunable circuits are demonstrated with this fabrication process.

Chapter 4

TUNABLE MICROWAVE FILTER USING BST VARACTORS

4.1 Introduction

Filters are indispensable in modern communication systems where accurate spectral control is needed. Tunable filters, especially, are becoming more desirable in the rapidly growing wireless communication industry, where mobile devices capable of operating over different frequency bands are of great interest. Novel tunable devices are needed for the design of such tunable filters. RF microelectro-mechanical systems (MEMS) and thin film ferroelectric varactors are two promising technologies that are currently under investigation. RF MEMS filters have been studied for continuously tuning mode [42] and digital-type tuning mode [43]. However, MEMS varactors suffers from large bias voltages (30 to 50 volts) and slow tuning speed in the range of 1-300 μ sec [1]. Ferroelectric based varactors have several merits, for example, lower tuning voltage (5 to 10 volts), fast response speed (approximate ns) and good quality factor [16]. Several works on tunable combline filters using ferroelectric varactors have been reported. In [44], thick BST film was used to form gap capacitors; while in [45] interdigital type capacitors were employed. Both of them asked for very large bias voltage because of poor usage of the tuning field. Filters employing parallel plate capacitor need much lower tuning voltage [46]. In this chapter, a fully integrated 2 GHz 3 pole tunable filter using BST varactors is presented with the design, fabrication and measurement results.



Figure 4.1 (a) Half wavelength, (b) quarter wavelength, (c) capacitvely loaded quarter wavelength and (d) capacitively loaded ring resonator

4.2 Capacitively Loaded Ring Resonators

Coupled resonator filters are commonly used in RF/microwave systems, especially in narrow-band bandpass filters applications. Two of the basic resonator structures are quarter-wave and half-wave transmission line resonators. In order to reduce the resonator's size, capacitors can be used to load the transmission line. The need of via holes not only complicates the fabrication but also introduces parasitics that cause extra loss and detune the resonance frequency. Instead, a capacitively loaded ring resonator is used with no need of vias as in Figure 4.1.

Four types of transmission line resonators are analyzed here. They are half wavelength resonators, quarter wavelength resonators, capacitively loaded quarter wavelength resonators and capacitively loaded ring resonators. The magnitude of input impedances of these four resonators are plotted as shown in Figure 4.2. All of the resonators have the shunt resonance at 1.8 GHz which results from an impedance pole. Both quarter-wave resonator and capacitively loaded ring resonator present an additional zero in contrast to quarter-wave and capacitively loaded quarter-wave resonator. The relative distance from the zero to the pole of resonators determines how sharp the filter's out-of-band rejection will be. Thus, the closer the zero to the pole, the steeper slope the filter will have. It is shown that filters employing capacitively loaded ring resonator have better rejection performance than those



Figure 4.2 Input impedance magnitude of (a) half wavelength, (b) quarter wavelength, (c) capacitively loaded quater wavelength and (d) capacitively loaded ring resonator

using other type of resonators.

The input admittance of the capacitively loaded ring resonator is analyzed in [47]

$$Y_{in} = Y_0 \frac{Y_0 sin\theta_t - 2\omega C_T (1 - cos\theta_T)}{Y_0 cos\theta_T - \omega C_T sin\theta_T}$$
(4.1)

where Y_0 is the characteristic admittance, C_T is loaded capacitor value, and θ_T is the electrical length of the transmission line. For the shunt resonant frequency at 1.8 GHz, the loaded capacitance is calculated to be 0.75 pF using (4.1) with θ_T of 100 degrees and characteristic impedance Z_0 of 50 Ω .

4.3 A Three Pole Bandpass Filter Design

A 3 pole bandpass filter with center frequency of 1.8 GHz and bandwidth of 6% is designed. From (4.2) and (4.3) [48], the mutual coupling coefficient between the two adjacent resonators and the input/output external resonators' Q are determined to be $M_{1,2} = M_{2,3} = 0.055$, $Q_{e1} = Q_{e3} = 17.2$.

$$M_{i,i+1} = \frac{FBW}{\sqrt{g_i g_{i+1}}} \tag{4.2}$$

$$Q_{ei} = \frac{g_{i-1}g_i}{FBW} \tag{4.3}$$

where FBW is the fractional bandwidth and g_i is the element value for low pass prototype. The full wave simulator IE3D [49] is used to determine the mutual coupling coefficient and the external Qs by the method described in [48]. In order to perform on wafer probe measurement, a microsotrip line to CPW transition is adopted from [50]. The filter layout is shown in Figure 4.3.



Figure 4.3 Layout of 3 pole tunable filter

The width of the ring transmission line is 347 μm with a characteristic impedance of 50 ohm. The spacing (S₁) between adjacent resonators is 320 μm , and tapping point (L₁)
for the input/output stage is 2120 μm . W_1 is 2200 μm , W_2 is 1070 μm , L_2 is 6200 μm and L_3 is 4000 μm . The signal line width of the CPW line is 50 μm , and the gap size is 28 μm .

4.4 Filter Fabrication

A single side polished sapphire (Al_2O_3) with 430 μm thickness and dielectric constant of 11.58 is used as substrate. The BST varactor is implemented by two parallel plate capacitors connected in series. The bottom electrode, which is a metal stack of Ti/Au/Pt (100/2000/1000 Å), is evaporated and patterned by a standard lift-off process. Then BST thin film is deposited by the pulsed layer deposition (PLD) technique using an excimer laser ($\lambda = 248$ nm, 25 ns pulse width, 10 Hz, 200 mJ) with substrate temperature of 600 °C in 30 mTorr oxygen environment for 60 minutes. After this, the sample is annealed at the same temperature in 100 Torr oxygen for 30 minutes to reduce oxygen vacancies in the BST film. The BST thin film has a thickness of 250 nm. The top electrode of Pt/Au (1000/2000 Å) is completed in the same process as the bottom electrode. A high resistivity material, SiCr, is deposited to form biasing lines for the varactors. SiCr thin film has a thickness of 720 Å and a sheet resistance of 800 ohm/sq. Each capacitively loaded ring resonator needs two bias lines, one of which is connected to the bottom electrode between two parallel capacitors in series. By doing this, these BST capacitors act as loading capacitors as well as DC blocking capacitors. The other line is connected to transmission line of the resonator. Then filter trace is patterned to 8 μm gold which is 4 times thicker than the skin depth at this frequency to reduce the metal loss. The fabricated filter is shown in Figure 4.4, and the inset shows the close view of BST varactor and SiCr biasing line. The total circuit size is 14 mm by 22 mm.



Figure 4.4 Micro-graph of fabricated 3 pole tunable filter

4.5 Filter Measurement Results

The input and output of the filter are connected to two 150 μm GSG probes, and the filter is measured by the Agilent E8364B VNA. On wafer through-reflection-line (TRL) calibration kit is used to calibrate out the CPW to microsotrip line transitions.

At zero bias, the center frequency of the filter is 2.05 GHz with an insertion loss of 6.4 dB. The return loss of the filter is better than 20 dB. The 3 dB bandwidth is found to be 8%, as shown in Figure 4.5. The shift of the center frequency and bandwidth from the design values may be due to the decrease of capacitance of the BST varactors.

On wafer testing BST varactors are measured, and the device performance is characterized by the two port measurement technique described in chapter 2. The extracted loss tangent is 0.021 over the desired frequency band, and the total device quality factor is 40. The insertion loss is mainly due to varactor's low quality factor. The insertion loss of the filter is simulated to be 5.9 dB when BST varactors exhibit Q factor of 40. Another source



Figure 4.5 Measured filter response when no DC bias is applied.

of the loss is from the SiCr bias line fed to the BST varactors. The loss contributed by this 800 ohm/sq bias line is simulated to be approximate 0.5 dB. With a DC bias voltage from 0 to 10 volts, the center frequency is varied from 2.05 GHz to 2.41 GHz which corresponds to a 20% tunability. The return loss is better than 10 dB over this frequency range, and the insertion loss increases from 6.4 dB to 9.9 dB as shown in Figure 4.6. The 3 dB bandwidth is nearly constant from 8% to 8.3% with 3.75% change.

4.6 Conclusion

A fully integrated 2 GHz 8% bandwidth tunable bandpass filter using BST varactor is designed, fabricated and measured. Capacitively loaded ring resonators are used to design this filter because they provide a easy way of frequency tuning and sharper filter out-of-



Figure 4.6 (a)Insertion loss and (b) return loss of the tunable microwave filter with DC bias voltage from 0 V to 10 V.

band rejection. The measured insertion loss of the filter at zero bias voltage is 6.4 dB with the BST varactor Q of 40. Under 10 volts bias, the filter can be tuned from 2.05 GHz to 2.41 GHz, giving a 20% center frequency tunability while the fractional bandwidth is kept constant. The return loss is lower than 10 dB over the entire tuning frequency range. The filter performance can be improved as the BST varactors' Q-factors are increased.

Chapter 5

SWITCHABLE ACOUSTIC WAVE RESONATORS AND FILTERS USING FERROELECTRIC THIN FILMS

5.1 Introduction

Multi-band and multi-mode wireless handsets are of great interest for the future wireless communications. These devices require a switchable filter bank to select the frequency band for each wireless standard. Switchable filter banks based on current filter technologies require external switches using solid state or MEMS devices. Incorporating external switches in the path of RF signal results in increased loss, circuit complexity and cost. In order to address these challenges, switchable acoustic wave resonators and filters using ferroelectric thin films are proposed here. Our aim is to use the electrostrictive or DC electric field induced piezoelectric effect which was first studied in the bulk ferroelectrics in the 1950's [51, 52]. Recently these effects have been observed in thin film ferroelectric materials [53, 54]. Acoustic wave resonators based on ferroelectric thin films can be effectively switched on and off by the application of a DC bias voltage. Therefore, no external switches are needed. Switchable filter banks using ferroelectric thin film based acoustic wave resonators can achieve higher cicuit performance, smaller footprint and lower cost. This chapter first discusses the electrostrictive effect in ferroelectric thin films. Then FBARs using BST thin film are presented along with a modeling method, fabrication process and the measurement results. Ladder type filters using ferroelectric thin film acoustic wave resonators are designed and experimentally demonstrated. Finally contour mode acoustic wave resonators using BTO thin films are studied, fabricated and measured.

5.2 Piezoelectricity and Electrostriction

Piezoelectricity was first discovered in 1880 by the Curie brothers. The piezoelectric effect desribes an electrical polarization induced by an mechanical stress in crystals. The converse piezoelectric effect is defined as an applied electric field inducing a strain. This relation is methematically defined as shown in (5.1) and (5.2).

$$S = s^E T + d^T E \tag{5.1}$$

$$D = dT + \varepsilon^T E \tag{5.2}$$

where S is strain, s is compliance, T is stress, D is electric displacement, d is piezoelectric coefficient, ε is permittivity, E is electric field strength; superscript E indicates a zero or constant electric field, and superscript T a zero or constant stress field.

The piezoelectric effect shows a linear relation between mechanical and electrical domains coupling, defined by piezoelectric coefficient d. There also exists a quadratic relation due to the electrostrictive effect. A general relation between the induced strain (S) and the electrical polarization (P) is describe in (5.3), assuming there's no applied stress.

$$S = QP^2 \tag{5.3}$$

where Q is the electrostriction coefficient. With the applied electric field, the polarization is defined as (5.4)

$$P = P_s + \chi E \tag{5.4}$$

where P_s is the spontaneous polarization, χ is the susceptibility and χE is the induced

polarization due to the applied electrical field E. From (5.3) and (5.4), one can obtain

$$S = QP_s^2 + 2QP_s\chi E + Q\chi^2 E^2$$
(5.5)

The total strain consist of three parts: the spontaneous strain, the linear piezoelectric strain, and the quadratic electrostrictive strain. Ferroelectric materials possess piezoelectric effects due to the spontaneous polarization caused by the non-centrosymmetrical crystal structure. The resultant piezoelectric effect shows hysteresis following the polarization hysteresis. In the paraelectric phase, there's no piezoelectric effect since the crystal structure is centrosymmetrical. Therefore, the electrostrictive effect dominates. Due to the electrical field dependant polarization, the electrostrictive effects are dependant on the applied electrical field. This unique property allows us to control the mechanical/electrical coupling by the applied DC bias voltage. The converse piezoelectric/electrostrictive effect can be used to generate acoustic waves. For piezoelectric material, the strength of the acoustic waves can only be changed by the amplitude of the AC electrical signal. In the ferroelectric materials, the generation and strength of the acoustic waves are dependant on the applied DC electric field.

A piezoelectric resonator is mainly made of a piezoelectric material such as quartz, aluminum nitride (AlN) or zinc oxide (ZnO). When an alternating electric field at the proper frequency is applied to the piezoelectric material, acoustic wave vibrations are excited through the direct and converse piezoelectric effects. The piezoelectric resonators can be excited into different resonance modes such as thickness mode, shear mode or contour mode, depending on which piezoelectric coefficient is used and the geometrical dimensions determining the resonance frequency. Using ferroelectric materials instead of piezoelectric materials, the acoustic wave resonance will be controlled by the DC bias voltage. Therefore switchable acoustic wave resonators can be fabricated using ferroelectric materials.



Figure 5.1 BST FBAR structure

5.3 Thickness Mode Acoustic Wave Resonators Design

Thin film bulk acoustic wave resonators (FBARs) are thickness mode acoustic wave resonators. The resonance frequency is inversely proportional to the resonator thickness. FBARs using ferroelectric thin films can be modeled in the same way as the FBARs using piezoelectric thin films such as aluminum nitride (AlN) and zinc oxide (ZnO). An acoustic wave transmission line model [55] is used to model FBARs using ferroelectric BST thin films here.

The BST FBAR is composed of Si substrate, SiO_2 buffer layer, bottom platinum electrode, BST thin film, and the top platinum electrode as shown in Figure 5.1. The fundamental resonance frequency is mainly determined by the longitudinal acoustic velocity in the BST thin film and its thickness as given by (5.6).

$$f_n = \frac{v_{ac}}{t_{BST}}n, \ n = 1, 2, 3, \dots$$
 (5.6)

where v_{ac} is the acoustic wave velocity in the BST thin film, and t_{BST} is the thickness

of the BST thin film.

The BST FBAR is loaded by the acoustic impedance of air at the top and bottom. Layers of Pt electrodes, SiO2 and Si substrate act like acoustic transmission lines that transfer the acoustic impedance of air to the BST thin film. The acoustic input impedance of each layer is given by (5.7)

$$Z = Z_{ac} \frac{Z_L + Z_{ac} tanh(\gamma t)}{Z_{ac} + Z_L tanh(\gamma t)}$$
(5.7)

where Z_{ac} is the acoustic characteristic impedance, t is the thickness, and γ is the propagation constant of each layer. The load impedance Z_L is the impedance presented by the previous layer. From the top electrode side, Z_L is the acoustic impedance of air. The acoustic impedance looking into the top Pt electrode side, Z_t , can be determined by using (5.7). The acoustic impedance looking into the bottom electrode side, Z_b , can be calculated again by using (5.7) through cascade of Si substrate, SiO_2 and Pt bottom electrode. Then the microwave input impedance of the BST FBAR can be calculated by

$$Z_{in} = \frac{1}{j\omega C} \left[1 - K^2 \frac{tan\phi}{\phi} \frac{(Z_t + Z_b)cos^2\phi + jsin2\phi}{(Z_t + Z_b)cos^2\phi + j(Z_t Z_b + 1)sin2\phi} \right]$$
(5.8)

where C is static capacitance of the BST capacitor determined by the electrode area, BST film thickness and its permittivity, K^2 is the electromechanical coupling coefficient of the BST thin film, and ϕ is half of the phase delay of acoustic waves traveling in the BST thin film.

BST FBARs with and without the silicon substrate are simulated using the model described above. The microwave input impedances for these two cases are calculated by (5.8) and the material parameters in Table 5.1. As shown in Figure 5.2, the resonance is weak when the silicon substrate is present underneath the BST FBAR. This is because the generated acoustic waves leak through the substrate. In other words, the substrate acts as a damping load to the resonator. When the silicon substrate is removed, the resonance be-

Layer	Acoustic wave velocity (m/s)	Acoustic impedance (kg/m^2s)	Thickness (nm)
Air	360	400	NA
BST	5640	33.5E6	500
Pt	3300	69.8E6	110
SiO_2	5100	12.55E6	600
Si	9000	21E6	3200

 Table 5.1
 Acoustic and physical parameters of the layers in BST FBAR

comes much stronger. Therefore it is necessary to remove the silicon substrate underneath BST FBARs completely. Another approach to reduce the substrate loading effect is to use Bragg reflectors which consist of alternating quater wave thick high and low acoustic impedance layers.



Figure 5.2 BST FBAR simulation comparison with/without the silicon substrate

5.4 Contour Mode Acoustic Wave Ring Resonator Design

In the FBAR technology, the piezoelectric thin film bulk is excited in the thickness mode through the piezoelectric coefficient d_{33} . The resonance frequency is predominantly determined by the piezoelectric thin film thickness. Therefore, fabrication of resonators and

filter banks with different center frequencies requires either several depositions with different deposition times, or thinning the piezoelectric layer by dry or wet etching process to achieve various thin film thickness. This repetitive process increases the fabrication cost and may cause thin film degradation. Furthermore, this process is not economical for the manufacturing of multiple-frequency FBAR filters on single chip. In order to address this challenge, a lateral or contour mode resonance excited through the piezoelectric coefficient d_{31} can be used instead of the thickness mode resonance. The resonance frequency of contour mode resonators is determined by the lateral dimensions of the resonator. Therefore fabrication of many resonators at the same time on a single wafer using standard photolithography techniques can be achieved. Furthermore, the tolerance of the resonance frequency to lateral dimension is larger than that to the thickness, resulting in a uniform distribution of the resonance frequency over the entire wafer. A schematic comparison of thickness mode and contour mode acoustic wave resonators is shown in Figure 5.3.



Figure 5.3 Thickness mode and contour mode acoustic wave resonators.

By using ferroelectric thin films instead of piezoelectric thin films, DC switchable contour mode acoustic wave resonators can be fabricated. The structure for contour mode resonators studied here is based on a ring resonator as shown in Figure 5.4. The resonance frequency is determined by the ring's width W given by (5.9) [19] where E_p is the Young's



Figure 5.4 Contour mode ring resonatorTable 5.2 Material properties of BTO thin films

Layer	Mass density (kg/m^3)	Poisson's ratio	Young's modulus (GPa)
BTO	5800	0.3	67

modulus, ρ is the mass density and σ is the Poisson's ratio of the ferroelectric thin film

$$f = \frac{1}{2W} \sqrt{\frac{E_p}{\sigma(1-\rho^2)}}$$
(5.9)

A DC switchable contour mode resonator using BTO thin films is simulated by using (5.9) and the material properties of BTO thin film in Table 5.2. The resonance frequency versus the ring width is plotted and shown in Figure 5.5. As predicted by (5.9), the resonance frequency is inversely proportional to the ring width. Ring widths smaller than 1.78 microns are required to achieve resonance frequencies above 1 GHz.

5.5 Ladder Type FBAR Filters Design

The most common filter topology for FBAR filters is the ladder type filter which consists of alternating series and shunt FBARs, as shown in Figure 5.6. The operation mechanism of a ladder type filter can be explained analytically by a single unit cell which consists of a series and a shunt FBAR as shown in Figure 5.7. Each FBAR has two resonance frequencies. One is the series resonance frequency f_s at which the impedance can be as low as 1



Figure 5.5 The relationship between resonance frequency and the lateral dimension of circular ring BTO thin film contour mode resonators.



Figure 5.6 Ladder type FBAR filter

Ω. The other one is the parallel resonance frequency f_p at which its impedance can be as high as several kΩ.

The shunt FBAR is tuned to a lower resonance frequency by mass loading of the electrodes of the resonator. When f_{p2} is tuned to be the same or slightly smaller than f_{s1} , a passband is formed around f_{p2} and f_{s1} . At f_{s1} a low impedance is present between the input and output of the L-section unit cell. While at f_{p2} , a high impedance is present between the output and the ground. Therefore the signal passes through the filter with a very small



Figure 5.7 One L-section in ladder type FBAR filters

attenuation. At f_{s2} , the associated low impedance shorts the input to the ground. Therefore, a transmission zero is created below the passband. At f_{p1} the high impedance is present between the input and output. Another transmission zero is created above the passband. Therefore a passband with two transmission zeros is achieved in ladder type FBAR filters.

When the frequency is far from f_s and f_p , each FBAR behaves as a capacitor with a static capacitance C. The L-section consists of a series capacitor C_1 and a shunt capacitor C_2 . The output to input voltage ratio of one L-section can be calculated by (5.10)

$$\frac{v_o}{v_i} = \frac{1}{1 + \frac{C_2}{C_1}} \tag{5.10}$$

For a ladder type FBAR filter with n L-section unit cells cascaded, the out-of-band rejection is determined by (5.11) which is plotted in Figure 5.8.

$$S_{21out-of-band} = \left(\frac{1}{1 + \frac{C_2}{C_1}}\right)^n \tag{5.11}$$



Figure 5.8 Out-of-band rejection versus capacitance ratio and the number of L-sections cascaded.

5.6 Fabrication Process and Measurement Results

5.6.1 BST FBARs

BST FBARs are fabricated on a 320 μm thick high resistivity silicon substrate (5 $k\Omega/\Box$). A layer of 6000 Å SiO₂ is deposited by plasma enhanced chemical vapor deposition (PECVD) because SiO₂ can be used as a very selective etch stop material in silicon etching process. Bottom electrodes (Ti/Pt 30/1000 Å) are then evaporated and patterned by a liftoff process. BST thin films are deposited by pulsed laser deposition (PLD) technique using an excimer laser (λ = 248 nm, 25 ns pulse width, 10 Hz, 1.75 J/cm^2) with a substrate temperature of 650 °C in 300 mTorr oxygen environment. Top electrodes (Pt 1000 Å) are patterned by evaporation and liftoff process to form the parallel plate capacitor. The measured thickness of BST thin films is 730 nm by Dektak surface profilometer. Before the probe pads (Cr/Au 200/5000 Å) are patterned, the wafer is annealed at 500 °C in flowing oxygen for 30 minutes to reduce the oxygen vacancies. The silicon substrate under the device area is

then removed by deep silicon reactive ion etch (DRIE) technique which can provide a 50:1 width to depth aspect ratio. Finally the exposed SiO2 underneath the device area is quickly removed by wet etching in acid. Therefore the actual BST FBARs have only 3 layers: top Pt electrode, BST thin film and bottom Pt electrode. The microscope image of a fabricated CPW fed BST FBAR device is shown in Figure 5.9.



Figure 5.9 Cross view and photograph of the fabricated BST FBAR

Reflection coefficients of BST FBARs are measured by a network analyzer using a 150 μm pitch size ground-signal-ground (GSG) probe. When no DC bias is applied, the device behaves as a normal capacitor. For electrode area of 80 μm by 80 μm , the capacitance value is 40 pF. As the DC bias is turned on and gradually increased to 25 V in steps of 5 V, the acoustic resonances are switched on and become stronger as shown in Figure 5.10.

The intersections of the impedance circles and the real axis of the smith chart determine the series and parallel resonance frequencies. At 25 V, the series (f_s) and parallel (f_p) resonance frequency is 1.975 and 2.035 GHz respectively. Based on the measured resonance frequencies, the effective electromechanical coupling coefficient is calculated to be 7.07% using (5.12) [55].

$$K_t^2 = \frac{\pi}{2} \frac{f_s}{f_p} tan(\frac{\pi}{2} \frac{(f_p - f_s)}{f_p})$$
(5.12)

The magnitude of the BST FBAR's input impedance is plotted in Figure 5.11. The BST FBAR exhibits a series resistance of 2.2 Ω and a shunt resistance of 94.3 Ω at f_s and f_p



Figure 5.10 Reflection coefficient of the BST FBAR when DC bias is (a) ON and (b) OFFTable 5.3 Modified Butterworth-Van Dyke circuit model for the fabricated BST FBAR

Circuit element	Co (pF)	Cm (pF)	Lm (nH)	Rm (Ohm)	Rs (Ohm)
Value	19.67	1.29	5.03	0.18	2.2

respectively. The corresponding unloaded quality factors are calculated to be233 at f_s and 218 at f_p by (5.13)

$$Q_L = \frac{f}{2} \frac{d\phi_{Z_{in}}}{df} \tag{5.13}$$

where $\phi_{Z_{in}}$ is the phase of input impedance of the BST FBAR.

The acoustic parameters of BST thin film are extracted through fitting to (5.8) with the measured results. The extracted acoustic velocity and quality factor of BST thin film are 5743 m/s and 1000 respectively. The modified Butterworth-Van Dyke (mBVD) circuit model [56] is fit into the measurement results as shown in Figure 5.12. The extracted equivalent circuit model of BST FBARs are given in Table 5.2.



Figure 5.11 Magnitude of the input impedance of the BST FBAR

5.6.2 A 1.5 Stage Ladder Type BTO FBAR Filter

A switchable 1.5 stage ladder FBAR filter has been designed and fabricated. The filter consists of two series resonators and two shunt resonators as shown in Figure 5.13. Each resonator is made of a BTO thin film sandwiched between two platinum electrodes. The total capacitance of the shunt resonators is chosen to be four times the capacitance of the series resonator in order to achieve a better out-of-band rejection. The symmetric placement of the shunt resonators allows for on wafer measurement using coplanar probes. The four BTO FBARs within the filter must be biased at the same voltage level for proper filter operation. This is accomplished by applying the bias voltage to the bottom electrode which is shared by the four resonators. The top electrodes are connected to DC ground. A high resistivity material SiCr is used for the DC bias line.

The BTO switchable FBAR filter is fabricated on a high resistivity silicon substrate (5 $k\Omega \dot{c}m$) with a thickness of 525 μm . A 1 μm thermal oxide buffer layer is deposited on top of the substrate. A 100 nm bottom electrode of platinum is patterned by e-beam evap-



Figure 5.12 (a) Modified Butterworth-Van Dyke model, (b) Measured reflection coefficient, fitted reflection coefficient using both acoustic transmission line model and modified Butterworth-Van Dyke model.



Figure 5.13 A schematic of 1.5 stage BTO FBAR filter.

oration and liftoff. A 700 nm BTO thin film is then deposited by pulsed laser deposition (PLD) technique using the same conditions as the BST FBAR in the previous section. The top electrode is deposited using the identical procedure for the bottom electrode. The four silicon release window are opened by wet etching BTO and SiO_2 thin films. A 60 nm high resistivity SiCr biasing line is RF sputtered and patterned by liftoff. The SiCr film has a



Figure 5.14 A photograph of the fabricated 1.5 stage BTO FBAR filter.

sheet resistance of 1.5 $k\Omega/\Box$. A 20 nm mass loading layer of gold is deposited on the shunt resonators for the frequency tuning. A 500 nm gold contact layer is deposited for the CPW and DC probe pads. Finally the silicon substrate underneath the filter is dry etched by XeF_2 which is an isotropic silicon etching process. A photograph of the fabricated switchable filter is shown in Figure 5.14. This filter has an area of 40 μm by 80 μm while a typical AIN FBAR resonator solely occupies 200 μm by 200 μm at this frequency [57].

The filter response is measured using a Cascade Microtech probe station, GGB groundsignal-ground probes and an Agilent E8364B vector network analyzer. The DC bias voltage is varied from -3 V to 15 V. When the DC bias is decreased to -3V, the filter is turned off and provides at least 15 dB of isolation as shown in Figure 5.15(a). As the DC bias is increased, the filter exhibits a passband with a decreasing insertion loss. With the application of a 15 V DC bias, the filter exhibits an insertion loss of 6.2 dB with 40 MHz bandwidth at 2.14 GHz. The out-of-band rejection is 20 dB and the return losses for both ports are better than -10 dB, as shown in Figure 5.15(b).



Figure 5.15 Measured filter response when (a) DC bias is -3 V and (b) DC bias is 15 V.



Figure 5.16 Comparison of measured and simulated filter response.

Both the series and the shunt resonators in the switchable filter are measured. The series resonators have a series resonance frequency of 2.14 GHz and an associated Q-factor of 97. The shunt resonators have a de-tuned series resonance frequency of 2.09 GHz and an associated Q-factor of 64. The electromechanical coupling coefficient is measured to be 4.2% for the series resonators and 4.9% for the shunt resonators. The static capacitance is measured to be 0.65 pF for the series resonators and 1.5 pF for the shunt resonators. Both the series and shunt resonators are modeled using the Butterworth-Van Dyke (BVD) circuit model. These models are used for the filter simulation. The simulated filter response matches well with the measurement results as shown in Figure 5.16. The large insertion loss is mainly due to the low Q-factor of the BTO FBARs. As the Q-factor is increase to 1000 which is a typical value for AlN FBARs [58], the insertion loss is improved to 2 dB in the simulation, as shown in Figure 5.16. Therefore, material study and optimization of ferroelectric thin films are necessary to achieve higher quality factors and better filter performance.



Figure 5.17 (a)Measurement results and (b) simulation results of two tone test of BTO FBAR filters.



Figure 5.18 (a) A photograph of the fabricated ferroelectric thin film ring contour mode acoustic wave resonator and (b) a closer view of it.

A two tone intermodulation measurement is conducted to characterize the linearity of the switchable filter. The IIP3 of the filter in the ON state is measured to be 26.2 dBm with the two tones at 2.14 and 2.141 GHz, as shown in Figure 5.17 (a). To study the origins of nonlinearities in the BTO FBAR filter, a two tone simulation has been done. Each FBAR is modeled with its BVD model. The nonlinear capacitance is modeled by the method described in [59]. The simulated IIP3 is 54.7 dBm, which is much better than the measured IIP3. Therefore, there must be other nonlinear effect other than the nonlinear capacitance in this filter. One possible origin of the nonlineairties may be from the quadratic electrostrictive effect in the ferroelectric thin films. Modeling of the nonlinear quadractive electrostrictive effect is not available at this stage. Future work need to be done in this topic.

5.6.3 Contour Mode Acoustic Wave Resonators

Ring contour mode acoustic wave resonators using both BST and BTO thin films have been fabricated with the same process as the BTO FBAR filter. The resonators are designed for a width of 10 μm . Due to the photolithography tolerance the ring width is increased to 12 μm . A photograph of a fabricated contour mode resonator is shown in Figure 5.18.



Figure 5.19 Measurement results of contour mode BST acoustic wave resonators when the DC bias voltage is changed from 0 V to 20 V.

The fabricated contour mode resonators are characterized using an Agilent E8364B vector network analyzer and a GGB ground-signal-ground (GSG) probe with a pitch size of 150 μm . For contour mode resonators using BST thin films, the DC bias voltage is changed from 0 V to 20 V. However very weak contour mode resonance has been observed, as shown in Figure 5.19. For contour mode resonators using BTO thin films, the DC bias voltage is gradually increased from 0 V to 12 V. When no DC bias is applied to the contour mode resonator, only a very weak resonance at 158 MHz is observed as shown in Figure 5.20 (a). This measurement result can be attributed to the phenomenon of spontaneous polarization seen in ferroelectric BTO thin films. When a 1 V DC bias is applied, the resonance disappears as shown in Figure 5.20 (a) because the spontaneous polarization is compensated by the external DC electric field. Therefore the resonator is effectively turned off at 1 V DC bias voltage. As the DC bias increases, the resonator is turned on. At 12 V



Figure 5.20 Measurement results of contour mode BTO acoustic wave resonatos when the DC bias voltage is (a) 0 V and 1 V and (b) 12 V.



Figure 5.21 Tuning of resonance frequencies of BTO contour mode resonators.

DC bias, the resonator exhibits a series resonance frequency fs of 159.7 MHz and a parallel resonance frequency fp of 160.45 MHz as shown in Figure 5.20 (b). At 12 V DC bias, the Q factors are calculated to be 47 and 83 for the series and parallel resonance frequency respectively using (5.13). The electromechanical coupling coefficient of the BTO thin film in this particular resonator is calculated to be 1.15% using (5.12). This electromechanical coupling coefficient is comparable to that of contour mode resonators using piezoelectric AlN thin films [60]. Both the series and the parallel resonance frequencies increase monotonically as the DC bias voltage increases as shown in Figure 5.21. Frequency tuning of 0.8% is achieved which is comparable to thickness mode SMRs using ferroelectric thin films [61].

5.7 Conclusion

Switchable acoustic wave resonators and filters have been demonstrated using ferroelectric thin films. They is based on the electrostrictive or electric field induced piezoelectric effect in ferroelectric thin films. Both thickness and contour mode resonators have been presented with the intrinsic switching property by the DC bias voltage. A 1.5 stage ladder type BTO FBAR filter has been designed, fabricated and measured with moderate insertion loss.

Chapter 6

CONCLUSIONS AND FUTURE WORK

6.1 Conclusions

Within this dissertation demonstration of switchable and tunable radio frequency components using ferroelectric thin films are presented for the first time. These devices are useful for reconfigurable wireless communication systems such as multi-band and multimode wireless mobile phones and cognitive radios. This work includes ferroelectric thin film deposition optimization, clean room fabrication process, BST varactors modeling and measurement techniques, a tunable microwave filter using BST varactors, and switchable acoustic wave resonators and filters based on ferroelectric thin films.

The presented two port measurement technique demonstrates both easier implementation and better accuracy than the commonly used one port reflection type measurement technique. The uncertainty analysis of both techniques shows that two port measurement technique is 30% less sensitive to the measurement errors than the one port measurement technique. This technique can be useful for material scientist and engineers to characterize the ferroelectric thin film in a confident way.

The PLD process is used to deposit ferroelectric thin films. By varying the deposition conditions, an optimized PLD process can yield BST thin films with low loss tangents and high tunabilities. Loss tangents of 0.01 has been achieved at lower GHz range for BST thin films. A full clean room fabrication process has been developed for fabrication of tunable microwave capacitors and circuits using BST thin films. Various fabricated varactors and tunable circuits have been demonstrated.

A fully integrated 2 GHz 3 pole tunable bandpass filter using BST varactors has been demonstrated. Capacitively loaded ring resonators are used in this filter to provide an easy tuning and a good out-of-band rejection. The fabricated filter exhibits a 20% frequency tunability with a moderate insertion loss.

Electrostrictive and electric field induced piezoelectric effects in the ferroelectric thin films have been studied to realize intrinsically switchable acoustic wave resonators and filters. Both thickness mode and contour mode switchable acoustic wave resonators have been successfully demonstrated. At a DC bias of 25 V, BST FBARs exhibit Q-factors exceeding 200 at 2 GHz, and a large electromechanical coupling coefficient of 7%. Contour mode resonance using BTO thin films are demonstrated at 150 MHz. A 1.5 stage ladder type BTO FBAR filter is designed, fabricated and measured. At a DC bias of -3 V, the filter is turned off. At a DC bias of 15 V, the filter is turned on. At the ON state, this filter exhibits 40 MHz bandwidth passband at 2.14 GHz with an insertion loss of 6.2 dB. The out-of-band rejection is better than 15 dB. This filter has a very compact size of 40 μm by 80 μm . This is much smaller than piezoelectric AIN FBAR filters. Therefore one can envision a switchable filter array in a very small footprint.

The demonstrated switchable and tunable RF components prove the ferroelectric thin film technology as a good candidate for future wireless communication systems. The next section will outline some ideas for the future work to improve and expand this technology.

6.2 Future Work

6.2.1 Low Temperature Deposition of Ferroelectric Thin Films Using Atomic Layer Deposition

All the current deposition techniques for ferroelectric thin films require a very high temperature exceeding 500 °C in order to achieve good crystalline films. However this prevents the integration of ferroelectric thin films to the modern IC process in which the highest tolerable process temperature is 400 °C. Atomic layer deposition (ALD) may provide a solution for low temperature deposition of ferroelectric thin films due to the strong chemical reaction among the precursor materials. ALD also have a number of merits such as, fine film thickness control, very good 3D conformal coating, very few defects and etc. Several groups have successfully demonstrated depositions of STO and BTO thin films using ALD in the temperature range of 200 - 350 °C [62, 63]. Films with permittivity exceeding 100 have been achieved. In [62] Vehkamaki found that large oxidant water dose can improve the film crystallinity without high temperature post process annealing. Recently an Oxford OpAL ALD system was installed in the clean room at the University of Michigan. This can help to initiate studies of ferroelectric thin films deposited by ALD at low temperatures.

6.2.2 Higher Frequency Switchable Contour Mode Resonators Using Ferroelectric Thin Films

The demonstrated contour mode resonator operates at 150 MHz. In order to operate at higher frequencies such as in the GHz range, the ring width is calculated to be less than 1 μm . A single ring with such narrow width will be mechanically vulnerable, thus pose yield problem. Instead, interdigitized contour mode resonators have been proposed for piezo-electric AlN thin films [64]. The interdigital structure not only helps on the mechanical toughness but also lowers the motional resistance which improves the impedance matching. Therefore, high frequency interdigitized contour mode resonators using ferroelectric thin films can be investigated. To realize small features such as sub-micron features, two major fabrication issues need to be solved. The first issue is the alignment of sub-micron features. This can be done by using a stepper aligner. The second issue is the etching of ferroelectric thin films. Wet etching method using diluted HF is currently used to etch ferroelectric thin films. The etching speed is about 15 nm/sec which is too fast for sub-micron features. Also it is experimentally found that the wet etching causes problems around the edges of devices. To solve this problem, dry etching method can be used. Several work

on dry etching of ferroelectric thin films have been reported [65, 66] with a moderate etch speed.

6.2.3 High Performance Switchable FBAR Filters Using Ferroelectric Thin Films

A BTO FBAR filter have been demonstrated with moderate insertion loss and out-of-band rejection. Also cascading more sections of FBARs, a better out-of-band rejection can be achieved at the expense of insertion loss. To lower the insertion loss, BTO FBARs need to have higher Q-factors. In the future, studies of the material optimization for high Q-factor should be carried out. One needs to understand the relation between the mechanical Q-factor of ferroelectric thin films and the deposition conditions.

Appendices

Appendix A

Ferroelectric Thin Film Based Tunable Capacitors and Circuits Fabrication Process

A.1 Starting wafer: Sapphire, single-side polished, Cplane, 430 μm.

- Dice and blow dry using N2 gas.
- Soak in hot Xylene for 30 min.
- Rinse in the DI water for 5 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

A.2 Bottom electrode evaporation and liftoff.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1813 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Soak in chlorobenzen (CBZ) for 5 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.

- Metal evaporation (Ti/Pt 30/1000 Å).
- Liftoff in Acetone for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

A.3 Ferroelectric thin film deposition by PLD.

- Load the substrate and heat up the substrate with 5 °C/min rate.
- Substrate temperature of 650 °C.
- Partial oxygen pressure of 300 mTorr.
- Laser fluence of $1 J/cm^2$
- In chamber oxygen annealing at 650 °C with 100 Torr oxygen for 1 hour.
- Cool down the substrate with 2 °C/min rate.

A.4 Top electrode evaporation and liftoff.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1813 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Soak in chlorobenzen (CBZ) for 5 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Metal evaporation (Pt 1000 Å).
- Liftoff in Acetone for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

A.5 High temperature oxygen annealing.

- Furnace temperature at 500 °C.
- Flow oxygen with 2 sccm rate.
- Anneal for 30 min.

A.6 Ferroelectric thin film wet etch.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Hard bake 110 °C for 1 min.
- Wet etch in HF:DI (1:10) solution. (etch rate is about 200 nm for 20 sec)
- Rinse in DI water for 3 min and N_2 blow dry.
- Inspect the film thickness by Dektak.
- Strip photoresist in aceton for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.

- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

A.7 Bias networks sputter and liftoff.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Soak in chlorobenzen (CBZ) for 5 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- RF sputter (SiCr 700 Å).
- Liftoff in Acetone for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

A.8 Contact metal evaporation and liftoff.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Soak in chlorobenzen (CBZ) for 5 min.

- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Metal evaporation (Ti/Au 500/5000 Å).
- Liftoff in Acetone for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

A.9 Passivation layer deposition by PECVD.

- High temp SiO2 or SiN deposition (380 °C).
- Every time deposit 1000 Å.
- Target thickness 5000-7000 Å.

A.10 Passivation layer wet etch.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.

- Hard bake 110 °C for 1 min.
- Wet etch in BHF solution.
- Rinse in DI water for 3 min and N_2 blow dry.
- Inspect the film thickness by Dektak.
- Strip photoresist in aceton for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

A.11 Circuit metal evaporation and liftoff.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Soak in chlorobenzen (CBZ) for 5 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Metal evaporation (Ti/Au 500/5000 Å).
- Liftoff in Acetone for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

A.12 Gold electro-plating.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 2000 rpm for 30 sec.
- Spin 9260 at 2000 rpm for 30 sec.
- Soft bake at 115 °C for 4.5 min.
- Image exposure 2 min at $20 \ mW/cm^2$.
- Develop in AZ400 for 2 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Gold electro-plating to 8-10 μm .
- Strip photoresist in PRS2000 for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

A.13 Metal etch back.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.

- Hard bake 110 °C for 1 min.
- Wet etch Au in gold etchant.
- Wet etch Ti in BHF solution.
- Rinse in DI water for 3 min and N_2 blow dry.
- Inspect the film thickness by Dektak.
- Strip photoresist in aceton for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

Appendix B

Ferroelectric Thin Film Based Switchable Acoustic Wave Resonators and Filters Fabrication Process

B.1 Starting wafer: high resistivity Silicon, 525 μm , with 1 μm thermal silicon dioxide.

- Dice and blow dry using N2 gas.
- Rinse in aceton for 3 min.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- Rinse in the DI water for 5 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

B.2 Bottom electrode evaporation and liftoff.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1813 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Soak in chlorobenzen (CBZ) for 5 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.

- Oxygen asher at 250mT and 80W for 60 sec.
- Metal evaporation (Ti/Pt 30/1000 Å).
- Liftoff in Acetone for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

B.3 SiO2 wet etch.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Hard bake 110 °C for 1 min.
- Wet etch in BHF solution.
- Rinse in DI water for 3 min and N_2 blow dry.
- Inspect the film thickness by Dektak.
- Strip photoresist in aceton for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

B.4 Ferroelectric thin film deposition by PLD.

- Load the substrate and heat up the substrate with 5 °C/min rate.
- Substrate temperature of 650 °C.
- Partial oxygen pressure of 300 mTorr.
- Laser fluence of $1 J/cm^2$
- In chamber oxygen annealing at 650 °C with 100 Torr oxygen for 1 hour.
- Cool down the substrate with 2 °C/min rate.

B.5 Top electrode evaporation and liftoff.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1813 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Soak in chlorobenzen (CBZ) for 5 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Metal evaporation (Pt 1000 Å).
- Liftoff in Acetone for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

B.6 High temperature oxygen annealing.

- Furnace temperature at 500 °C.
- Flow oxygen with 2 sccm rate.
- Anneal for 30 min.

B.7 Ferroelectric thin film wet etch.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Hard bake 110 °C for 1 min.
- Wet etch in HF:DI (1:10) solution. (etch rate is about 200 nm for 20 sec)
- Rinse in DI water for 3 min and N_2 blow dry.
- Inspect the film thickness by Dektak.
- Strip photoresist in aceton for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

B.8 Bias networks sputter and liftoff.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Soak in chlorobenzen (CBZ) for 5 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- RF sputter (SiCr 700 Å).
- Liftoff in Acetone for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

B.9 Contact metal evaporation and liftoff.

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 4000 rpm for 30 sec.
- Spin 1827 at 4000 rpm for 30 sec.
- Soft bake at 105 °C for 1 min.
- Soak in chlorobenzen (CBZ) for 5 min.
- Image exposure 10 sec at $20 \ mW/cm^2$.
- Develop in MF319 for 1 min.
- Rinse in DI water for 3 min and N_2 blow dry.

- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Metal evaporation (Ti/Al/Ti/Au 500/15000/500/5000 Å).
- Liftoff in Acetone for at least 1 hour.
- Rinse in isopropyl alcohol (IPA) for 3 min.
- N_2 blow dry.
- Dehydration bake 130 °C for 3 min.

B.10 Silicon Micromechining Process

B.10.1 First generation: back side deep reactive ion etching (DRIE) using STS

- Apply HMDS to substrate and let it stay for 30 sec.
- Spin HMDS at 2000 rpm for 30 sec.
- Spin 9260 at 2000 rpm for 30 sec.
- Soft bake at 115 °C for 4.5 min.
- Back side alignment and image exposure 2 min at $20 \ mW/cm^2$.
- Develop in AZ400 for 2 min.
- Rinse in DI water for 3 min and N_2 blow dry.
- Check the pattern under microscope.
- Oxygen asher at 250mT and 80W for 60 sec.
- Bond with another silicon wafer using 1827.
- Bake in oven at 120 °C for 30 min.
- DRIE silicon etch using STS (etch 500 μm silicon for 2.5 hours).
- Inspect the wafer using Zygo for etch rate.
- Strip photoresit in PRS2000 overnight.
- Rinse in isopropyl alcohol (IPA) for 3 min.

- Spin dry the wafer.
- Dehydration bake 130 °C for 3 min.

B.10.2 Second generation: top side etching using XeF2

- Silicon etch using XeF2.
- Inspect the wafer under microscope.

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